

## CHANNEL LIST

## DAAB AUTOMATIC CONTROL UNIT EP105



CAUTION: For full instructions refer to the EP105 Instruction Manual and other documentation supplied.

## Safety

CAUTION: Important safety instructions. Following these instructions is important for personal safety. Retain these instructions.
\ Carefully read through this instruction manual in its entirety - it contains important information about safety, installation, commissioning and use. Particularly important safety information is identified with the symbol $\triangle$ in the left margin.
If you fail to follow the safety instructions in this instruction manual, there is a risk of serious damage to property or injury to animals or people. You should keep this instruction manual in a safe place for future use.
The EP105 or a unit controlled by the EP105 can be used by children from the age of 8 years and by people with physical, sensory or mental disabilities or inadequate experience and knowledge if supervised, or if they are given instructions on how to use the EP105 or a unit controlled by the EP105 and understand the dangers that may arise.
Children must not play with the installation or the controlled units. Cleaning and maintenance must not be carried out by children.
The EP105 control unit or the accessories recommended by FAAC Nordic AB must not be modified without the explicit consent of FAAC Nordic AB.
Only qualified persons working in their own fields may perform installation, adjustment, commissioning, repair and other work.
Electrical connections may only be made by qualified electricians, who accept responsibility for the connections.
Follow the safety instructions of the equipment to be controlled by the control unit.

## - Safety classification

FAAC Nordic AB has validated the safety circuits in the EP105 to performance level PL = c and Category 2 as defined in SS-EN ISO 13849-2:2008.
The EP105 is designed with safety edge inputs and an integrated load guard for use in personal safety applications. These features are designed to meet the requirements of the Machinery Directive 2006/42/EC.
The validation process assumed a technical service life of 10 years or 1 million operating cycles for components in safety circuits.
FAAC Nordic is unable to guarantee this validation when the motor contactors and safety edges exceed this technical service life. For this reason, these components should be replaced before the end of their service life.

## Operation

## - General

Anyone installing or modifying the EP105 must have documented knowledge and understanding of its functions, as well as experience of setting up the control system for the application in which it will be used.
Take care when operating internal buttons to avoid touching live components.
The unit may only be connected by a qualified electrician, who accepts responsibility for ensuring that the electric connections have been carried out in accordance with the applicable standards and this instruction manual.
Anyone commissioning the EP105 must have documented knowledge and understanding of its functions, as well as experience of commissioning control systems for the application in which it is used.

## - Service and maintenance

Regular inspection is required of the external safety features of the EP105, such as safety edges, stop buttons, photocells, load guards and safety loops. The condition of the enclosure, cables and installation must also be checked. This inspection must be carried out at least twice a year.

CAUTION: The EP105 must be disconnected from its power supply during cleaning, maintenance and when replacing parts or carrying out repairs.

## - Resetting/replacing tripped fuses

If the fuse protecting the power supply to the automatic control unit trips, FAAC Nordic AB recommends following these steps to reset/replace it.

- Switch off the main switch to the automatic control unit.
- Decouple the motor unit.
- Reset or replace the fuse.
- Switch on the main switch to the automatic control unit.
- Check that none of the drive units start before receiving the control signal.
- Check that the drive units can be started and stopped from the control buttons.
- If the drive unit cannot be stopped, contact FAAC Nordic AB.


## Connection

CAUTION: Important safety instructions. Follow all instructions, as incorrect installation can cause serious injury.

- Safety

The electrical connections may only be made by a qualified electrician, who accepts responsibility for ensuring that the electric connections have been carried out in accordance with the applicable standards and this instruction manual.
Always disconnect the power supply when connecting the control box. Mechanical installation of the control unit must be carried out by persons with the necessary knowledge for the task.

## - Installation

The location of the control unit must be selected with regard to the protection class of the enclosure, at least IP54. A heating and/or cooling element should be included if necessary to maintain the operating temperature stated in the technical specification.
The control unit must be securely fixed to a wall or a bracket intended for this purpose, using screw joints. The fixing holes are on the rear or underside of the enclosure.
Cables into and out of the enclosure must have cable entry seals that are approved for use with the particular cable. Cables outside the enclosure must be securely fixed to the surrounding structure. They must not hang loose and there must be no possibility of them catching on passing objects.

- High current

The power supply must be connected via a lockable main switch, and have T10A protection. Connect the incoming earth to the earth bar.
Check that the power supply and motor voltage are compatible.

## - Motors

The largest motor that can be connected is 1.5 kW (3-phase $3 \times 400 \mathrm{~V}$ ). See "Commissioning" for details of how to check the direction of rotation.

Connecting motors to EP105

Supply $3 \times 400 \mathrm{~V}$ with neutral


Supply $3 \times 230 \mathrm{~V}$ without neutral


For information about connecting to a frequency converter, see the instructions for add-in card DB409.

## Supply 1x230V with neutral (symmetrical)



If a symmetrical single-phase motor is used (as shown on the left) make the following changes.

EP105-1: Swap the cable at X12: L1-1 with X12: L1-C1.

EP105-2: Remove the cable between X11: L2-1 and X4: L2-2.
Swap the cable at X12: L1-1 with X12: L1-C1. Swap the cable at X7: L1-2 with X7:L1-C2. See the diagram below for the terminal locations.

Transformer


## Supply 1x230V with neutral (asymmetrical)



## - Connecting a safety edge

The safety edge resistor must be installed in the safety edge so that an open-circuit in the resistor or the cable is interpreted as actuation of the device. See the wiring diagram below. SE.C1 and SE. 01 must be used for a safety edge connected to the half to which motor 1 is connected, and SE.C2 and SE.O2 to the half to which motor 2 is connected.
The impedance can be between $1.0-9.9 \mathrm{k} \Omega$ with a $1 \%$ tolerance and a power capability of at least 0.5 W . FAAC Nordic AB recommends an impedance of $8.2 \mathrm{k} \Omega$. A safety edge can only be connected in series.
When connecting in series, only one resistor is used in the outermost safety edge, as shown in the wiring diagram below. The maximum number of safety edges connected in series with an impedance of $8.2 \mathrm{k} \Omega$ is six per input.
Note that the impedance used for a safety edge must be checked and entered into the EP105 on commissioning, see Commissioning below.

$\triangle$
Other types of impedance safety edge must not be connected directly to the safety edge inputs - they require an external control unit.
See the instruction manual for these safety edges.
Use only safety edges approved by FAAC Nordic AB.

- Connecting safety edges and photocells

The diagram below illustrates how to connect an external safety edge unit.


- Connecting an encoder (electronic limit switch)

The EP105 supports DB405 type encoders. The encoder uses the same terminals as a conventional mechanical limit switch. The two diagrams below illustrate how to connect the encoder, and they also show which is the left and right motor from the point of view of the automatic control unit. Make sure the cable to the encoder does not share the same buried pipe as the motor power supply.


- Connecting a mechanical limit switch (microswitch)



## - Connecting timer control limit switches

Limit switches can still be used with timer control - they are connected as shown above (mechanical limit switch) but only for the open position. If there is no limit switch, make the connections as shown below. A mechanical stop in the open position must be fitted.


## - Signal reference

Safety edge 1, closing movement (SE.C1)

Safety edge 2, closing movement (SE.C2)


Safety edge 1, opening movement (SE.O1) Safety edge 2, opening movement (SE.O2)


Stop input 1

Stop input 2

Stop input 3
Power supply encoder or common limit switch motor 1 Signal encoder or limit switch open motor 1 Limit switch closed motor 1 Power supply encoder or common limit switch motor 2
Signal encoder or limit switch open motor 2
Limit switch closed motor 2
Shared programmable input $1 \& 2$
Prog. input 1, Open, Pulse, P160
Prog. input 2, Close, Pulse, P260
Shared programmable input 3 \& 4
Prog. input 3, Open, Constantly, P360
Prog. input 4, Close, Constantly, P460
Shared programmable input 5 \& 6
Programmable input 5, P560
Programmable input 6, P660


Input for photocell or external vehicle detector




- Low current

$\triangle$The safety circuit, safety edge or limit switch must not be connected to, or used for, any other function. If signals from the EP105 are needed, a separate output card must be used.
The connection instructions are the same for all types of application, but not all signals may be needed.
If stop signals are unused, the associated input signals must be jumpered on the terminal block, see "Signal reference".
$\triangle$ Note that the 24 V for the stop circuit must not be combined with other 24 V circuits.

Technical specification

| Dimensions (WxHxD) | 190x224x60 mm. |
| :---: | :---: |
| Power supply | 3-phase or single-phase. |
| Power supply | $3 \times 400 \mathrm{~V}+\mathrm{N}+\mathrm{PE}, 3 \times 230 \mathrm{~V}+\mathrm{PE}, 1 \times 230 \mathrm{~V}+\mathrm{N}+\mathrm{PE}, 3 \times 400 \mathrm{~V}+\mathrm{PE}$ (requires an external transformer) |
| Permitted voltage variation | $\pm 10 \%$ |
| Frequency | 50 Hz . |
| Motor in 3-phase operation $3 \times 400 \mathrm{~V}$ | 3 -phase asynchronous motor 0.18-1.5 kW. |
| Motor in 3-phase operation $3 \times 230 \mathrm{~V}$ | 3 -phase asynchronous motor $0.18-0.75 \mathrm{~kW}$. |
| Motor in single-phase operation | Single-phase motor with capacitor 0.18-0.37 kW. |
| Fuses | External fuse max. T10A. |
| Power consumption | Automatic control unit $22 \mathrm{VA}+$ electric motors. |
| Operating mode | Intermittent operation $50 \%$ / maximum period of operation 2 minutes |
| Temperature range | 0 to $45^{\circ} \mathrm{C}$. |
| Safety edge | 2 closing inputs SE.C1 and SE.C2 for a safety edge while closing. |
|  | 2 opening inputs SE.O1 and SE.O2 for a safety edge while opening. |
|  | Variable impedance 1.0-9.9 k $\Omega$, power capability at least 0.5 W . |
| Safety circuit | Maximum resistance $3 \Omega$ total in the whole safety circuit. |
|  | Cable length at $0.75 \mathrm{~mm}^{2}$ max 60 m . Cable length at $1.5 \mathrm{~mm}^{2} \max 120 \mathrm{~m}$. |
| Internal motor protection | Setting range 0.5-6 A. |
| Load guard | Setting range 0.05-1.99 kW. |
| Programmable inputs | 6x |
|  | Low level 0-8 VDC, high level 12-30 VDC. |
|  | Input current 6 mA at 24 VDC . |
|  | Cable length maximum 200 metres at cable cross-sectional area $0.75 \mathrm{~mm}^{2}$ ( $\varnothing 1 \mathrm{~mm}$ ) |
| Limit switch/Encoder | 2+2 inputs |
|  | Input current 2 mA at encoder and 22 mA at limit switch |
|  | Cable length mechanical limit switches maximum 200 metres at cable cross-sectional area $0.75 \mathrm{~mm}^{2}(\varnothing 1 \mathrm{~mm})$ <br> Cable length DB405 maximum 50 metres at cross-sectional area $0.75 \mathrm{~mm}^{2}(\varnothing 1 \mathrm{~mm})$ |
| Photocell | 1 input |
|  | Low level 0-8 VDC, high level 12-30 VDC |
|  | Input current 6 mA at 24 VDC . |
|  | Cable length maximum 200 metres at cable cross-sectional area $0.75 \mathrm{~mm}^{2}$ ( $\varnothing 1 \mathrm{~mm}$ ) |
|  | Supply voltage 24 VDC max 50 mA . |
| External supply | Unregulated 24 VDC, 18-28 VDC, max 300 mA |
| Degree of protection | The PCB is designed for an enclosure rating of at least IP54. |

## Quick guide for commissioning of gate

- Conditions

Electrical installation has been carried out and drive units are disconnected. Commission one drive unit at a time only and start with drive unit 1. The supply voltage in C202 is set to $0,3 \times 400 \mathrm{~V}$ with neutral. The limit switch is of the encoder type. The display channel C999 is set to 2 . The indicators for safety edge are unlit. The indicators for photocell, stop circuit and 24 V are lit green

## - Commissioning of drive unit 1

Direction of movement: Start L001 to 4, hold-to-run without limits. Check that the motor arm attachment is running in the right direction by pressing the OPEN or CLOSE buttons on the automatic control unit. For change of direction of rotation, see section on Connection in EP105 Instruction Manual.

Open and closed position: Connect the gate half to drive unit 1 and enter the positions for open and closed. After this, L001 is set to 1 , encoder.


Motor protection: Read the motor current during operation in C251 and enter this value in C252 for opening and in C253 for closing. E201 means that the entered value is set too low. E206 means that the entered value is set too high.

Load guard: Set C999 to 3. In a swing gate application personal protection is not normally required, and C230 is set to 0.00 . Set C033 to 3, pulse to activate the load guard. After the load guard has tripped, the indication M1 flashes and the message n071 or n072 is shown on the display and in the error code list in C903. Check that the setting in the load guard in C232 and C233 is at just the right height not to cause material damage, but at the same time is sufficiently high to be guaranteed to open depending on weather conditions and mechanical changes.

Safety edges: Check the safety edges on gate half 1 by activating the safety edges during movement. Note that safety edge function in opening is closed in C131. In activated safety edge during closing, the gate must reverse to the fully open position, while in opening it must reverse to the closed position during the time in C494. Flashing indication for SE.C1 or SE.O1 means that the safety edge has been activated, but is now disabled.

## - Commissioning of drive unit 2

Preparations: C999 is set to 2 . Open half 1 and set L001 to 0 to keep drive unit 1 in open position. Set C033 to 5, service position.
Direction of movement: Start L002 to 4, hold-to-run without limits. Check that the motor arm attachment is running in the right direction by pressing the OPEN or CLOSE buttons on the automatic control unit. For change of direction of rotation, see section on Connection in EP105 Instruction Manual.
Open and closed position: Connect the gate half to drive unit 2 and enter the positions for open and closed. After this, L002 is set to 1, encoder.


Motor protection: Read the motor current during operation in C261 and enter this value in C262 for opening and in C263 for closing. E202 means that the entered value is set too low. E207 means that the entered value is set too high.

Load guard: C999 is set to 3. In a hinged gate application personal protection is not normally required, and C240 is set to 0.00 . Set C 033 to 3 , pulse to activate the load guard. After the load guard has tripped, the indication M2 flashes and the message n073 or n074 is shown on the display and in the error code list in C903. Check that the setting in the load guard in C242 and C243 is at just the right height not to cause material damage, but at the same time is sufficiently high to be guaranteed to open depending on weather conditions and mechanical changes.

Safety edges: Check the safety edges on gate half 2 by activating the safety edges while moving. Note that safety edge function in opening is closed in C141. In activated safety edge during closing, the gate must reverse to the fully open position, while in opening it must reverse to closed position during the time in C494. Flashing indication for SE.C2 or SE.O2 means that the safety edge has been activated, but is now disabled.

Additional boards: Set C999 to 4. Channels C702 to C712 show or hide channels for additional boards. If e.g. DB407, Output board, to be used set C707 to 1

Finishing: Set C999 to 0, display of all channels. Set L001 to 1, encoder and make fine adjustments to the gate halves in closed position using L113 and L123. Note all changed channels in EP105 Instruction Manual and the Log Book.

## Channel list

There are seven channel categories, each with its own letter and each handling different functions in the card.

- C-channels: General readout and configuration channels.
- d-channels: Channels relating to the DB402 vehicle detector.
- F-channels: Channels relating to settings for frequency converter, DB409
- L-channels: Channels relating to limit switches and timer control and the DB405 encoder.
- o-channels: Channels relating to output cards DB407 and DB410.
- P-channels: Channels relating to programmable inputs.
- r-channels: Channels relating to function of the DB411 radio card.

There is a reference column for each channel, showing where you can find more details and examples of how to use the channel, and the functions you can access with the channel.

## Channels with a grey background are readout channels so they cannot be changed.

The s symbol means that the channel is a safety setting, and any change in value must be documented in the log book, with a name and date.

## - General, C-channels

General readout channels
No. Name $\quad$ Range $\quad$ Fetting

General configuration channels


| C063 | Reverse priority during movement |  |  |  |  |  | $0-3$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | None |  |  |  |  |  |  |  |
|  | 1 | Open |  |  |  |  |  |  |  |
|  | 2 | Close |  |  |  |  |  |  |  |
|  | 3 | Open and close |  |  |  |  |  |  |  |

Safety edge


| $\triangle$ C103 | Function of safety edge input during test of external <br> safety edge unit | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 1 | Low resistance during test |  |  |
|  | 2 | High resistance during test |  |  |


| $\triangle C 104$ | Connection and safety edge function |  |  | $1-3$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 1 | SE.C1 or SE.C2 can be connected to either motor 1 or motor 2. <br> SE.O1 or SE.O2 can be connected to either motor 1 or motor 2. <br> Both safety edges reverse/stop an active motor |  |  |
|  | 2 | SE.C1 and SE.O1 must be connected to motor 1 <br> SE.C2 and SE.O2 must be connected to motor 2 <br> The safety edge function is attached to the motor concerned |  |  |
|  | 3 | SE.C1 or SE.C2 can be connected to either motor 1 or motor 2. <br> SE.O1 can be connected for protection function in opening for motor 1 and motor 2. <br> The safety edges reverse/stop an active motor <br> SE O2 stops an active motor in both opening and closing and overrides channel C142 |  |  |


| C105 | Halved speed after activated safety edge. <br> Only when using a frequency converter. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Active |  |  |


| $\triangle$ C111 | Selects function for safety edge SE.C1 |  |  | $0-2$ | 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | SE.C1 disabled |  |  |  |
|  | 1 | Limits according to set value in C 115 |  |  |  |
|  | 2 | Fixed limits between $5 \mathrm{k} \Omega$ and $15 \mathrm{k} \Omega$ |  |  |  |


| $\triangle$ C112 | Reverse/stop with activated safety edge SE.C1 (KSS) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | $1-2$ | 1 |  |  |  |
|  | 1 | Reverse |  |  |  |
|  | 2 | Stop |  |  |  |


| $\triangle$ C113 | Control of external protection connected to SE.C1 |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | No check | 1 |  |  |
|  | 1 | Test of protection connected to SE.C1 if C102 is enabled |  |  |  |


| C114 | Reading impedance SE.C1 | $00.0-99.9 \mathrm{k} \Omega$ |
| :--- | :--- | :--- |


| $\triangle C 115$ | Setting impedance value for safety edge SE.C1 <br> Set to 1 only at C111. | $1.0-9.9 \mathrm{k} \Omega$ | 8.2 |  |
| :--- | :--- | :--- | :--- | :--- |


| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| © C121 | Selects function for safety edge SE.C2 |  | 0-2 | 2 |  |
|  | 0 | SE.C2 disabled |  |  |  |
|  | 1 | Limits according to set value in C125 |  |  |  |
|  | 2 | Fixed limits between $5 \mathrm{k} \Omega$ and $15 \mathrm{k} \Omega$ |  |  |  |
| $\triangle$ C122 | Reverse/stop with activated safety edge SE.C2 |  | 1-2 | 1 |  |
|  | 1 | Reverse |  |  |  |
|  | 2 | Stop |  |  |  |
| © C123 | Control of external protection connected to SE.C2 |  | 0-1 | 1 |  |
|  | 0 | No check |  |  |  |
|  | 1 | Test of protection connected to SE.C2 if C102 is enabled |  |  |  |


| C124 | Reading impedance SE.C2 | $00.0-99.9 \mathrm{k} \Omega$ |  |  |
| :--- | :--- | :--- | :--- | :--- |
| C125 | Setting impedance value for safety edge SE.C2 <br> Set to 1 only at C121. | $1.0-9.9 \mathrm{k} \Omega$ | 8.2 |  |


| $\triangle$ C131 | Selects function for SE.O1 |  |  |  |  |  | $0-2$ | 0 |  |
| :---: | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | SE.O1 disabled |  |  |  |  |  |  |  |
|  | 1 | Limits according to set value in C 135 |  |  |  |  |  |  |  |
|  | 2 | Fixed limits between $5 \mathrm{k} \Omega$ and $15 \mathrm{k} \Omega$ |  |  |  |  |  |  |  |


| $\triangle$ C132 | Reverse/stop with activated safety edge SEO1 | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Reverse |  |  |
|  | 2 | Stop |  |  |


| $\triangle$ C133 | Control of external protection connected to SE.O1 |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $0-1$ | 1 |  |  |  |  |
|  | 0 | No check |  |  |  |
|  | 1 | Test of protection connected to SE.O1 if C102 is enabled |  |  |  |


| C134 | Reading impedance SE.O1 | $00.0-99.9 \mathrm{k} \Omega$ |  |  |
| :--- | :--- | :--- | :--- | :--- |
| C 135 | Setting impedance value for safety edge SE.O1. Set to <br> 1 only at C131. | $1.0-9.9 \mathrm{k} \Omega$ | 8.2 |  |


| $\Delta$ C141 | Selects function for SE.O2 |  |  |  |  |  | $0-2$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | SE.O2 disabled |  |  |  |  |  |  |  |
|  | 1 | Limits according to set value in C 135 |  |  |  |  |  |  |  |
|  | 2 | Fixed limits between $5 \mathrm{k} \Omega$ and $15 \mathrm{k} \Omega$ |  |  |  |  |  |  |  |


| $\triangle$ C142 | Reverse/stop with activated safety edge SE.02 <br> Subordinate to channel C104 | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 1 | Reverse |  |  |
|  | 2 | Stop |  |  |


| $\triangle$ C143 | Control of external protection connected to SE.O2 |  |  |  | $0-1$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | No check |  |  |  |  |
|  | 0 |  |  |  |  |
|  | 1 | Test of protection connected to SE.O2 if C102 is enabled |  |  |  |


| C144 | Reading impedance SE.O2 | $00.0-99.9 \mathrm{k} \Omega$ |
| :--- | :--- | :--- |


| $\triangle \mathrm{C} 145$ | Setting impedance value for safety edge SE.O2. Set to <br> 1 only at C141. | $1.0-9.9 \mathrm{k} \Omega$ | 8.2 |  |
| :--- | :--- | :--- | :--- | :--- |

Load guard and motor settings

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| © C200 | Load guard function |  | 0-4 | 3 |  |
|  | 0 | Disabled. Service and troubleshooting only |  |  |  |
|  | 1 | Reverse when closing, stop when opening |  |  |  |
|  | 2 | Stop when closing and reverse when opening |  |  |  |
|  | 3 | Reverse when closing and opening |  |  |  |
|  | 4 | Stop when closing and opening |  |  |  |
| $\triangle$ C202 | Type of power supply |  | 0-5 | 0 |  |
|  | 0 | $3 \times 400 \mathrm{~V}$ with neutral |  |  |  |
|  | 1 | 3x230 Vwithout neutral |  |  |  |
|  | 2 | $1 \times 230 \mathrm{~V}$ with neutral, asymmetrical |  |  |  |
|  | 3 | $3 \times 400 \mathrm{~V}$ without neutral (see separate instructions) |  |  |  |
|  | 4 | $1 \times 230 \mathrm{~V}$ with neutral, frequency converter (See DB409) |  |  |  |
|  | 5 | $1 \times 230 \mathrm{~V}$ with neutral, symmetrical |  |  |  |


| C205 | Load guard for personal protection active during the <br> closing movement | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Active |  |  |


| $\triangle C 211$ | Load guard delay | $0.01-2.50$ seconds | 0.06 |  |
| :--- | :--- | :--- | :--- | :--- |
| $\triangle C 212$ | Load guard, connection delay on start, all starts | $0.1-2.5$ seconds | 1.0 |  |
| $\triangle C 221$ | Motor protection delay | $3.0-5.0$ seconds | 5.0 |  |
| $\triangle C 230^{A C}$ | Set motor power readout for personal protection, <br> motor 1 | 0.00 and $0.12-0.35 \mathrm{~kW}$ | 0.20 |  |


| $\mathrm{C} 231^{\mathrm{A}}$ | Motor power readout, motor 1 | $0.00-1.99 \mathrm{~kW}$ |  |  |
| :--- | :--- | :--- | :--- | :--- |
| $\triangle \mathrm{C} 232^{\mathrm{A}}$ | Set load guard limit for motor 1 opening | $0.05-1.99 \mathrm{~kW}$ | 0.70 |  |
| $\triangle \mathrm{C} 233^{\mathrm{A}}$ | Set load guard limit for motor 1 closing | $0.05-1.99 \mathrm{~kW}$ | 0.70 |  |
| $\triangle \mathrm{C} 240^{\mathrm{BC}}$ | Set motor power readout for personal protection, <br> motor 2 | 0.00 and $0.12-0.35 \mathrm{~kW}$ | 0.20 |  |


| $\mathrm{C} 241^{\mathrm{B}}$ | Motor power readout, motor 2 | $0.00-1.99 \mathrm{~kW}$ |
| :--- | :--- | :--- |


| $\triangle \mathrm{C} 242^{\mathrm{B}}$ | Set load guard limit for motor 2 opening | $0.05-1.99 \mathrm{~kW}$ | 0.70 |  |
| :--- | :--- | :--- | :--- | :--- |
| $\triangle \mathrm{C} 243^{\mathrm{B}}$ | Set load guard limit for motor 2 closing | $0.05-1.99 \mathrm{~kW}$ | 0.70 |  |


| $\mathrm{C} 251^{\mathrm{A}}$ | Motor current readout, motor 1 | $0.0-20.0 \mathrm{~A}$ |
| :--- | :--- | :--- |


| $\triangle \mathrm{C} 252^{\mathrm{A}}$ | Set motor current readout, motor 1 opening | 0.0 and $0.5-6.0 \mathrm{~A}$ | 0.8 |  |
| :--- | :--- | :--- | :--- | :--- |
| $\triangle \mathrm{C} 253^{\mathrm{A}}$ | Set motor current readout, motor 1 closing | 0.0 and $0.5-6.0 \mathrm{~A}$ | 0.8 |  |
| $\triangle \mathrm{C} 261^{\mathrm{B}}$ | Motor current readout, motor 2 | $0.0-20.0 \mathrm{~A}$ |  |  |
| $\triangle \mathrm{C} 262^{\mathrm{B}}$ | Set motor current readout, motor 2 opening | 0.0 and $0.5-6.0 \mathrm{~A}$ | 0.8 |  |
| $\triangle \mathrm{C} 263^{\mathrm{B}}$ | Set motor current readout, motor 2 closing | 0.0 and $0.5-6.0 \mathrm{~A}$ | 0.8 |  |


| $\mathrm{C} 271^{\mathrm{AC}}$ | Power factor readout motor 1 | $0.00-0.99 \cos \varphi$ |
| :--- | :--- | :--- |
| $\mathrm{C} 281^{\mathrm{BC}}$ | Power factor readout motor 2 | $0.00-0.99 \cos \varphi$ |

$A=$ Not shown as L001 $=0 ; B=$ Not shown as L002 $=0, C=$ Not shown as C202 $=4$

Photocell

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C340 | Safety function in closing movement |  | 0-3 | 1 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Reverse to fully open |  |  |  |
|  | 2 | Stop with automatic restart of automatic closing |  |  |  |
|  | 3 | Stop, wait for new control signal or time in C520 and thereafter automatic closing. |  |  |  |


| C341 | Safety during run-on time or disengagement angle in <br> closing movement. | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled when both halves are in run-on or disengagement angle |  |  |
|  | 1 | Activated according to C340 |  |  |


| C342 | Safety function in opening movement |  |  |  | $0-4$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | 0 |  |  |
|  | 1 | Reverse to fully closed. |  |  |  |
|  | 2 | Stop with automatic restart of automatic closing |  |  |  |
|  | 3 | Stop, wait for new control signal or time in C520 and thereafter automatic closing. |  |  |  |
|  | 4 | Stop with restart of opening |  |  |  |


| C343 | Check of external protection connected to input <br> PHOTO | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | No check |  |  |
|  | 1 | Test of break in continuity for protection connected to input PHOTO |  |  |


| C351 | Photocell closing after time in C510 |  |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |  |
|  | 1 | Enabled and subordinated to C340 |  |  |  |  |  |  |  |  |


| C354 | Type of photocell closing |  |  | $1-2$ | 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Closes immediately if photosensor is disabled |  |  |  |
|  | 2 | Continues to fully open, then closes if photocell is disabled |  |  |  |

General time channels.

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\triangle$ C436 | Type of stop during run-on time when closing, subordinated to C448 and C449 |  | 0-3 | 3 |  |
|  | 0 | Time |  |  |  |
|  | 1 | Time or load guard |  |  |  |
|  | 2 | Time or safety edge |  |  |  |
|  | 3 | Time, load guard or safety edge |  |  |  |


| $\triangle$ C448 | Safety edge reverse during run-on while closing, L117, <br> L127, L213, L223 | $0-2$ | 2 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Function disabled |  |  |
|  | 1 | Safety edge reverse during run-on time |  |  |
|  | 2 | Safety edge reverse during run-on time and during the time in C492 |  |  |


| $\triangle$ C449 | Reverse during run-on time when load guard is <br> triggered, L117, L127, L213, L223 | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Reversing in closing movement |  |  |


| C460 | Time delay before second motor starts. <br> Start of motor 2 is delayed during opening <br> Start of motor 1 is delayed during closing | $0.1-9.9$ seconds | 0.1 |  |
| :--- | :--- | :--- | :--- | :--- |


| C470 | Time delay before first motor starts. <br> Start of motor 1 is delayed during opening <br> Start of motor 2 is delayed during closing | $0.00-0.99$ seconds | 0.00 |  |
| :--- | :--- | :--- | :--- | :--- |


| $\triangle$ C492 | Change of direction delayed if PHOTO, LOOP1 <br> LOOP2 or control signal are activated. | $0.1-4.0$ seconds | 0.8 |  |
| :--- | :--- | :--- | :--- | :--- |


| $\triangle$ C493 | Reverse delay if safety edge or load guard are activated | $0.03-2.00$ seconds | 0.10 |  |
| :--- | :--- | :--- | :--- | :--- |
| $\triangle$ C494 | Closing time after activated protection function, safety <br> edge or load guard, while opening | $0.1-2.0$ seconds | 1.0 |  |
| C495 | Engagement time for brake, motor 1 | $00,10-50 \mathrm{~ms}$ | 00 |  |
| C496 | Engagement time for brake, motor 2 | $00,10-50 \mathrm{~ms}$ | 00 |  |

Automatic closing

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C500 | Time before automatic closing 000,0 means disabled function |  | 000.0-600.0 seconds | 000.0 |  |
| C510 | Time before closing, after passage, on photocell closing and loop closing. <br> Subordinated to C351, d151 and d251 |  | 00-99 seconds | 00 |  |
| C520 | Blocking time for automatic closing after the stop button is activated. 000 means disabled function. |  | $\begin{aligned} & 000 \text { and } 020-600 \\ & \text { seconds } \end{aligned}$ | 000 |  |
| C591 | Closing using photocell and loops. See also C351, d151 and d251. |  | 00-14 | 00 |  |
|  | $00 \quad$ Disabled |  |  |  |  |
|  | 01 | Presence detection, LOOP1 must first be activated, closes when LOOP1 is clear. |  |  |  |
|  | 02 | Presence detection, LOOP2 must first be activated, closes when LOOP2 is clear. |  |  |  |
|  | 03 | Presence detection, LOOP1 and LOOP2 must first be activated simultaneously, closes when either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 04 | Presence detection, PHOTO must first be activated, closes when PHOTO is clear. |  |  |  |
|  | 05 | Presence detection, PHOTO and LOOP1 must first be activated simultaneously, then close when either PHOTO or LOOP1 is clear. |  |  |  |
|  | 06 | Presence detection, PHOTO and LOOP2 must first be activated simultaneously, then close when either PHOTO or LOOP2 is clear. |  |  |  |
|  | 07 | Presence detection, PHOTO, LOOP1 and LOOP2 must first be activated simultaneously, close when either PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
|  | 08 | Presence detection, LOOP1 or LOOP2 must first be activated, close when both LOOP1 and LOOP2 is clear. |  |  |  |
|  | 09 | Direction sensing, LOOP1 must first be activated, during the time LOOP2 must be activated, then LOOP1 must be disabled, closes when LOOP2 is clear. |  |  |  |
|  | 10 | Direction sensing, LOOP1 must first be activated, during the time PHOTO must be activated, then LOOP1 must be disabled, closes when PHOTO is clear. |  |  |  |
|  | 11 | Direction sensing, LOOP2 must first be activated, during the time LOOP1 must be activated, then LOOP2 must be disabled, closes when LOOP1 is clear. |  |  |  |
|  | 12 | Direction sensing, LOOP2 must first be activated, during the time PHOTO must be activated, then LOOP2 must be disabled, closes when PHOTO is clear. |  |  |  |
|  | 13 | Direction sensing, PHOTO must first be activated, during the time LOOP1 must be activated, then PHOTO must be disabled, closes when LOOP1 is clear. |  |  |  |
|  | 14 | Direction sensing, PHOTO must first be activated, during the time LOOP2 must be activated, then PHOTO must be disabled, closes when LOOP2 is clear. |  |  |  |


| No. | Name | Range | Factory | Setting |
| :--- | :--- | :--- | :--- | :--- | :--- |
| C600 | Choice of communication | $0-2$ | 0 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Interlock |  |  |
|  | 2 | Simply connect |  |  |

## Interlock

| C610 | Choice of unit address | $1-2$ | 2 |  |
| :--- | :--- | :--- | :--- | :--- |
| C614 | Block of local door |  |  | $0-3$ |
|  | 0 | No blocking of the local door depending on position of remote door |  |  |
|  | 1 | Block of open on local door until remote door is closed |  |  |
|  | 2 | Block of open on local door until remote door is open |  |  |
|  | 3 | Blocking of close on local door until remote door is closed |  |  |


| C615 | In block of local door | $0-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Stopped local door does not disable blocking of remote door. Local door does not remember open <br> and stop |  |
|  | 1 | Stopped local door does not disable blocking of remote door. Local door remembers open and stop. |  |
|  | 2 | Stopped local door disables blocking of remote door. Local door does not remember open and stop |  |
|  | 3 | Stopped local door disables blocking of remote door. Local door remembers open and stop |  |

## Simply connect

| C621 | Channel access | $0-1$ | 1 |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Reading only |  |  |  |
|  | 1 | Reading and writing | $0000-9999$ | 0000 |  |
|  | Simply connect pin code |  |  |  |  |

## Configuration

| C700 | Selection of application | $0-7$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Not selected |  |  |
|  | 1 | Gate, Swing gate |  |  |
|  | 2 | Gate, Folding gate |  |  |
|  | Gate, Sliding gate |  |  |  |
|  | Door, Swing door |  |  |  |
| 5 | Door, Folding door |  |  |  |
|  | 6 | Door, Sliding door |  |  |
|  | 7 | Barrier |  |  |


| C701 | Magnetic lock control DB310 |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | Not installed, does not affect display of channels |  |  |  |  |  |  |  |
|  | 1 | Installed |  |  |  |  |  |  |  |


| C702 | Vehicle detector card DB402 |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Not installed, d-channels not displayed | 0 |  |  |
|  | 1 | Installed | $0-1$ |  |  |
| C705 | Encoder card DB405 |  |  |  |  |
|  | 0 | Not installed, does not affect display of L-channels | 0 |  |  |
|  | 1 | Installed, the settings in L001 and L002 also control display of L-channels |  |  |  |


| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C707 | Output card DB407 |  | 0-1 | 0 |  |
|  | 0 | Not installed, o-channels not displayed |  |  |  |
|  | 1 | Installed |  |  |  |
| C709 | Interface card DB409 |  | 0-1 | 0 |  |
|  | 0 | Not installed, does not affect display of F-channels |  |  |  |
|  | 1 | Installed, selection in channel C202 also controls display of the F-channels |  |  |  |
| C710 | Output card DB410 |  | 0-1 | 0 |  |
|  | 0 | Not installed, o-channels not displayed |  |  |  |
|  | 1 | Installed |  |  |  |
| C711 | Radio card DB411 |  | 0-1 | 0 |  |
|  | 0 | Not installed, r-channels not displayed |  |  |  |
|  | 1 | Installed |  |  |  |
| C712 | Communication card DB512 |  | 0-1 | 0 |  |
|  | 0 | Not installed, does not affect display of channels |  |  |  |
|  | 1 | Installed |  |  |  |

## Service channels



- Vehicle detector DB402, d-channels

Vehicle loop 1
Note that the display of the d-channels is determined by the setting in C702


| No. | Name | Range | Factory |  | Setting |
| :--- | :--- | :--- | :--- | :--- | :--- |
| d160 | Control function | $0-1$ | 0 |  |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |


| d161 | Type of control signal when activated |  |  |  | $1-2$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Pulse | 1 |  |  |
|  | 2 | Constant signal when loop is activated |  |  |  |


| d162 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |


| d163 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |  |


| d170 | Allows the opening function, via LOOP1, using a <br> programmable input. |  |  | $0-6$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, normal opening/closing function. (Programmable input has no function for LOOP1) |  |  |
|  | Opening possible only if there is a signal at programmable input 1 |  |  |  |
|  | Opening possible only if there is a signal at programmable input 2 |  |  |  |
|  | 3 | Opening possible only if there is a signal at programmable input 3 |  |  |
|  | Opening possible only if there is a signal at programmable input 4 |  |  |  |
|  | 5 | Opening possible only if there is a signal at programmable input 5 |  |  |
|  | 6 | Opening possible only if there is a signal at programmable input 6 |  |  |


| d 175 | Opening via loop after activation during set time, the <br> loop will not open the gate until it has been activated <br> for the set time. | $0.0-9.9$ seconds | 0.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| d190 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if d160 is set to 1, "Open" |  |  |

Vehicle loop 2
Note that the display of the d-channels is determined by the setting in C702


| d 241 | Safety during run-on time or disengagement angle in <br> closing movement. | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Activated according to P240 |  |  |


| d242 | Safety function in opening movement |  |  | $0-4$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Reverse to fully closed |  |  |  |
|  | 2 | Stop with automatic restart of automatic closing |  |  |  |
|  | 3 | Stop without automatic restart of automatic closing, wait for new control signal |  |  |  |
|  | 4 | Safety only in closed position. Used when the gate passes over the loop in the opening movement. |  |  |  |


| d251 | Loop closing after time in C510 |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |
|  | 1 | Enabled |  |  |  |  |  |  |  |


| d254 | Type of loop closing |  |  | $1-2$ | 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Close immediately when loop is disabled |  |  |  |
|  | 2 | Continues to fully open, then closes when the loop is disabled |  |  |  |


| No. | Name | Range | Factory |  | Setting |
| :--- | :--- | :--- | :--- | :--- | :--- |
| d260 | Control function | $0-1$ | 0 |  |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |


| d261 | Type of control signal when activated |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Pulse |  |  |  |  |  |  |  |
|  | 2 | Signal when loop is activated |  |  |  |  |  |  |  |


| d262 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |


| d263 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |  |


| d270 | Allows the opening function, via LOOP2, using a <br> programmable input. | $0-6$ | 0 |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, normal opening/closing function. (Programmable input has no function for LOOP2) |  |
| 1 | Opening possible only if there is a signal at programmable input 1 |  |  |
| 2 | Opening possible only if there is a signal at programmable input 2 |  |  |
| 3 | Opening possible only if there is a signal at programmable input 3 |  |  |
| 4 | Opening possible only if there is a signal at programmable input 4 |  |  |
| 5 | Opening possible only if there is a signal at programmable input 5 |  |  |
|  | 6 | Opening possible only if there is a signal at programmable input 6 |  |


| d 275 | Opening via loop after activation during set time, the <br> loop will not open the gate until it has been activated <br> for the set time. | $0.0-9.9$ seconds | 0.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| d290 | Interlock opening |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Sends open signal to remote door, if d260 is set to 1, "Open" |  |  |  |

- Frequency converter, F-channels
No.

|  | Name | Range | Factory | Setting |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| F001 | Communication with frequency converter | $0-1$ | 1 |  |  |
|  | 0 | Communication disabled |  |  |  |
|  | 1 | Communication activated | $0.5-9.9$ seconds | 2.0 sec |  |
| F002 | Acceleration time from closed position <br> motors 1 and 2 (from $0-100 \mathrm{~Hz})$ |  |  |  |  |


| F003 | Acceleration time in all movements except at closed <br> position motors 1 and 2 (from $0-100 \mathrm{~Hz})$ | $0.5-9.9$ seconds | 4.0 sec |  |
| :--- | :--- | :--- | :--- | :--- |
| F004 | Acceleration time when P500 is set to 2 and the input <br> is activated, battery backup | $5.0-12.0$ seconds | 7.0 sec |  |


| F005 | Retardation time with limit switch and change of <br> direction motors 1 and $2($ from $1000-0 \mathrm{~Hz})$ | $0.5-9.9$ seconds | 4.0 sec |  |
| :--- | :--- | :--- | :--- | :--- |


| F006 | Retardation time with photocell and vehicle loops <br> motors 1 and $2($ from 1000 Hz$)$ | $0.5-9.9$ seconds | 2.0 sec |  |
| :--- | :--- | :--- | :--- | :--- |


| F008 | Low-speed frequency for opening movement | $5-20 \mathrm{~Hz}$ | 5 Hz |  |
| :--- | :--- | :--- | :--- | :--- |
| F009 | Low-speed frequency for closing movement | $5-20 \mathrm{~Hz}$ | 10 Hz |  |
| F012 | Opening frequency / Opening speed for motor 1 | $21-99 \mathrm{~Hz}$ | 50 Hz |  |
| F013 | Closing frequency / Closing speed for motor 1 | $21-99 \mathrm{~Hz}$ | 30 Hz |  |
| F014* | Number of degrees with low-speed frequency before <br> open position for motor 1 | $0-60$ | 0 |  |


| F015* | Number of degrees with low-speed frequency before <br> closed position for motor 1 | $0-60$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |


| F022 | Opening frequency / Opening speed for motor 2 | $21-99 \mathrm{~Hz}$ | 50 Hz |  |
| :--- | :--- | :--- | :--- | :--- |
| F023 | Closing frequency / Closing speed for motor 2 | $21-99 \mathrm{~Hz}$ | 30 Hz |  |


| F024* | Number of degrees with low-speed frequency before <br> open position for motor 2 | $0-60$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |


| F025* | Number of degrees with low-speed frequency before <br> closed position for motor 2 | $0-60$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |

* = Appears only when L001 and/or L002 are set to 1 encoder or 4, hold-to-run without limit switch.

F-channels are shown only when C2020=4, frequency converter

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| F030* | Choice of ratio for motor 1 |  | 0-9 | 0 |  |
|  | 0 | Not selected, in this position the motor only rotates at 25 Hz |  |  |  |
|  | 1 | MK with pulleys 40/71 (gear ratio 1318:1) |  |  |  |
|  | 2 | MK with pulleys 50/71 (gear ratio 1098:1) |  |  |  |
|  | 3 | MK with pulleys 71/71 (gear ratio 791:1) |  |  |  |
|  | 4 | MK with pulleys 100/71 (gear ratio 565:1) |  |  |  |
|  | 5 | MK with pulleys 125/71 (gear ratio 456:1) |  |  |  |
|  | 6 | MK with pulleys 140/71 (gear ratio 409:1) |  |  |  |
|  | 7 | MT (ratio 791:1) |  |  |  |
|  | 8 | M10 with pulleys 71/71, motor $1400 \mathrm{rev} / \mathrm{min}$ (gear ratio 2970:1) |  |  |  |
|  | 9 | M10 with pulleys 71/71, motor $2800 \mathrm{rev} / \mathrm{min}$ (gear ratio 1485:1) |  |  |  |


| F031* | Measured ratio motor 1. Only when F030=0. | $0-2000$ |
| :--- | :--- | :--- |


| F040* | Choice of ratio for motor 2 |  | 0-9 | 0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | Not selected, in this position the motor only rotates at 25 Hz |  |  |  |
|  | 1 | MK with pulleys 40/71 (gear ratio 1318:1) |  |  |  |
|  | 2 | MK with pulleys 50/71 (gear ratio 1098:1) |  |  |  |
|  | 3 | MK with pulleys 71/71 (gear ratio 791:1) |  |  |  |
|  | 4 | MK with pulleys 100/71 (gear ratio 565:1) |  |  |  |
|  | 5 | MK with pulleys 125/71 (gear ratio 456:1) |  |  |  |
|  | 6 | MK with pulleys 140/71 (gear ratio 409:1) |  |  |  |
|  | 7 | MT (ratio 791:1) |  |  |  |
|  | 8 | M10 with pulleys 71/71, motor $1400 \mathrm{rev} / \mathrm{min}$ (gear ratio 2970:1) |  |  |  |
|  | 9 | M10 with pulleys 71/71, motor $2800 \mathrm{rev} / \mathrm{min}$ (gear ratio 1485:1) |  |  |  |


| F041* | Measured ratio motor 2. Only when F040=0. | $0-2000$ |
| :--- | :--- | :--- |

* = Appears only when L001 and/or L002 are set to 1 encoder or 4, hold-to-run without limit switch.

F-channels are shown only when C2020=4, frequency converter

- Limit switches, L-channels

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L001 | Choice of limit switch type for motor 1 |  | 0-3 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Encoder |  |  |  |
|  | 2 | Limit switch |  |  |  |
|  | 3 | Time |  |  |  |
|  | 4 | Hold-to-run without limit switches. NOTE! Only one half at a time can be run. C033 must be set to 5 . |  |  |  |
| L002 | Choice of limit switch type for motor 2 |  | 0-3 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Encoder |  |  |  |
|  | 2 | Limit switch |  |  |  |
|  | 3 | Time |  |  |  |
|  | 4 | Hold-to-run without limit switches. NOTE! Only one half at a time can be run. C033 must be set to 5 . |  |  |  |

Encoder

| L110 $^{1}$ | Position of motor 1, viewed from the motor side |  |  | $0-2$ | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Left |  |  |  |
|  | 2 | Right |  |  |  |


| L111 $^{1}$ | Position angle readout motor 1 | $000-360$ degrees |  |  |
| :--- | :--- | :--- | :--- | :--- |
| L112 $^{1}$ | Angle for open position, motor 1 | $145-330$ degrees | 260 |  |


| L113 $^{1}$ | Angle for closed position, motor 1 | $015-200$ degrees | 90 |  |
| :--- | :--- | :--- | :--- | :--- |
| L116 $^{1}$ | Angle for partial opening, motor 1. | $0-200$ degrees | 45 |  |


| L117 $^{1}$ | Angle for disconnection of safety edge, load guard <br> and photocell from the end of the closing movement, <br> motor 1 in combination with C436, C341 and C448 | $0-30$ degrees | 0 |  |
| :--- | :--- | :--- | :--- | :--- |


| L118 $^{1}$ | Angle for the disconnection of vehicle loops from the <br> end of the closing movement, motor 1 in combination <br> with d141 or d241. | $0-45$ degrees | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
| $\mathrm{~L} 120^{2}$ | Position of motor 2, viewed from the motor side |  |  |  |
|  | 0 | Disabled | $0-2$ | 2 |
|  | 1 | Left |  |  |
|  | 2 | Right |  |  |


| L121 $^{2}$ | Position angle readout motor 2 | $000-360$ degrees |  |  |
| :--- | :--- | :--- | :--- | :--- |
| L122 $^{2}$ | Angle for open position, motor 2 | $145-330$ degrees |  |  |


| L123 $^{2}$ | Angle for closed position, motor 2 | $015-200$ degrees | 90 |  |
| :--- | :--- | :--- | :--- | :--- |
| L126 $^{2}$ | Angle for partial opening, motor 2. | $0-200$ degrees | 45 |  |


| ${\mathrm{L} 127^{2}}$ | Angle for disconnection of safety edge, load guard <br> and photocell from the end of the closing movement, <br> motor 2 in combination with C436, C341 and C448 | $0-30$ degrees | 0 |  |
| :--- | :--- | :--- | :--- | :--- |


| L128 $^{2}$ | Angle for the disconnection of vehicle loops from the <br> end of the closing movement, motor 2 in combination <br> with d141 or d241. | $0-45$ degrees | 0 |  |
| :--- | :--- | :--- | :--- | :--- |

1 = Only displayed if L001 is set to 1 or 4.2 = Only displayed if L002 is set to 1 or 4 .

Limit switch

| No. | Name | Range | Factory |  | Setting |
| :--- | :--- | :--- | :--- | :--- | :--- |
| L203 $^{\text {A }}$ | Setting limited running time (Not used with encoder) | $001-999$ seconds | 001 |  |  |
| L211 $^{\text {A }}$ | Running time readout, motor 1 | $000-999$ seconds |  |  |  |
| L212 $^{\text {AB }}$ | Run-on time following limit switch open, motor 1 | $0.00-7.99$ seconds | 0.00 |  |  |
| L213 $^{\text {A }}$ | Run-on time following limit switch closed, motor 1 | $0.00-7.99$ seconds | 0.00 |  |  |
| L216 $^{\text {A }}$ | Set partial opening time, motor 1 | $00.3-99.9$ seconds | 05.0 |  |  |
| L221 $^{\text {A }}$ | Running time readout, motor 2 | $000-999$ seconds |  |  |  |
| L222 $^{\text {AC }}$ | Run-on time following limit switch open, motor 2 | $0.00-7.99$ seconds | 0.00 |  |  |
| L223 $^{\text {A }}$ | Run-on time following limit switch closed, motor 2 | $0.00-7.99$ seconds | 0.00 |  |  |
| L226 $^{\text {A }}$ | Set partial opening time, motor 2 | $00.3-99.9$ seconds | 05.0 |  |  |

## Time control

| L311 | Time readout for motor 1 | $00.1-99.9$ seconds |  |  |
| :--- | :--- | :--- | :--- | :--- |
| L312 $^{\text {A }}$ | Set time for motor 1 | $00.1-99.9$ seconds | 00.1 |  |
| L321 | Time readout for motor 2 | $00.1-99.9$ seconds |  |  |
| L322 | Set time for motor 2 | $00.1-99.9$ seconds | 00.1 |  |

A $=$ Only displayed if L001 and/or L002 are set to 2 or 3 .
B = Only displayed if $\mathrm{L} 001=1$ and $\mathrm{C} 202=4$, frequency converter
C $=$ Only displayed if $L 002=1$ and $\mathrm{C} 202=4$, frequency converter.

## - Output card DB407 and DB410, o-channels

## Programmable output 1

Note that the display of the o-channels is determined by the setting in C707 and C710


| o114 | Delayed switch-off Switch off after the specified time <br> Used for example for lighting that is switched off a <br> specified time after closing. | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o120 | Pre-warning time before start | $000.0-600.0$ seconds | 000.0 |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| o121 | Pre-warning function in combination with o120 |  |  |  |  | $1-4$ | 2 |  |
|  | 1 | Constant signal before automatic closing |  |  |  |  |  |  |
|  | 2 | Constant signal before park and automatic closing |  |  |  |  |  |  |
|  | 3 | Constant signal before close signal, park and automatic closing |  |  |  |  |  |  |
|  | 4 | Constant signal before all movements |  |  |  |  |  |  |


| o122 | Function during pre-warning time in other output |  |  |  | $1-2$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Output signal disabled | 1 |  |  |
|  | 2 | Output signal as configured in o110-o112 |  |  |  |



| o130 | Alarm delay. Alarm in channels o131 - o142 must be <br> active in this time to produce output signal. | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o131 | Alarm if pressed safety edge. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o132 | Alarm for critical error message in display | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o133 | Alarm if stop circuit interrupted |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o134 | Alarm if door open | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o135 | Alarm if door is in mid position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o136 | Alarm if door is in closed position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o137 | Alarm if vehicle loop 1 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o138 | Alarm if vehicle loop 2 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o139 | Alarm if photocell interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o142 | Alarm for uncritical error message in display. <br> E008, E015, E028, E046, E047, E048, E201, E202, <br> E206, E207, E931, E932 | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o183 | Inversion of contact function for output |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Normally open, NO |  |  |  |  |  |  |  |
|  | 2 | Normally closed, NC |  |  |  |  |  |  |  |


| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o191 | Function when LOOP2, LOOP2 or PHOTO activated |  | 01-14 | 01 |  |
|  | 01 | Presence detection. Signal when LOOP1 is activated, remains until LOOP1 is clear. |  |  |  |
|  | 02 | Presence detection. Signal when LOOP2 is activated, remains until LOOP2 is clear. |  |  |  |
|  | 03 | Presence detection. Signal when both LOOP1 and LOOP2 are activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 04 | Presence detection. Signal when PHOTO is activated, remains until PHOTO is clear. |  |  |  |
|  | 05 | Presence detection. Signal when PHOTO and LOOP1 are activated, remains until either PHOTO or LOOP1 is clear. |  |  |  |
|  | 06 | Presence detection. Signal when PHOTO and LOOP2 are activated, remains until either PHOTO or LOOP2 is clear. |  |  |  |
|  | 07 | Presence detection. Signal when PHOTO, LOOP1 and LOOP2 are activated, remains until either PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
|  | 08 | Presence detection. Signal when either LOOP1 or LOOP2 is activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 09 | Direction sensing. Signal when first LOOP1 and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |
|  | 10 | Direction sensing. Signal when first LOOP1 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 11 | Direction sensing. Signal when first LOOP2 and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 12 | Direction sensing. Signal when first LOOP2 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 13 | Direction sensing. Signal when first PHOTO and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 14 | Direction sensing. Signal when first PHOTO and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |

Programmable output 2
Note that the display of the o-channels is determined by the setting in C707 and C710

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o200 | Function of output 2 |  | 0-4 | 1 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Position indication/Movement/Warning. Signal as configured in o210-o222 |  |  |  |
|  | 2 | Presence detection/Direction sensing. Signal as configured in o291 |  |  |  |
|  | 3 | Lock |  |  |  |
|  | 4 Alarm output. Signal as configured in o214, o230-o242 | Alarm output. Signal as configured in o214, o230-o242 |  |  |  |
| o210 | Open position |  | 0-1 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o211 | Mid position |  |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |  |
|  | 1 | Constant signal |  |  |  |  |  |  |  |  |


| o212 | Closed position | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o213 | Movement |  |  | $0-4$ | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal in the opening movement |  |  |  |
|  | 2 | Constant signal in the closing movement |  |  |  |
|  | 3 | Constant signal in the opening and closing movement |  |  |  |
|  | 4 | No signal during movement, used in combination with o210, o211 and o212. |  |  |  |


| o214 | Delayed switch-off Switch off after the specified time <br> Used for example for lighting that is switched off a <br> specified time after closing | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o220 | Pre-warning time before start | $000.0-600.0$ seconds | 000.0 |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| o221 | Pre-warning function in combination with o220 |  |  |  |  | $1-4$ | 2 |  |
|  | 1 | Constant signal before automatic closing |  |  |  |  |  |  |
|  | 2 | Constant signal before park and automatic closing |  |  |  |  |  |  |
|  | 3 | Constant signal before close signal, park and automatic closing |  |  |  |  |  |  |
|  | 4 | Constant signal before all movements |  |  |  |  |  |  |


| o222 | Function during pre-warning time in other output |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | $1-2$ | 1 |  |  |
|  | 2 | Output signal disabled |  |  |  |



| o231 | Alarm if pressed safety edge. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Constant signal |  |  |
|  | 1 | Active |  |  |


| o232 | Alarm for critical error message in display |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Constant signal |  |  |  |
|  | 1 | Active |  |  |  |


| o233 | Alarm if stop circuit interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o234 | Alarm if door open | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o235 | Alarm if door is in mid position |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o236 | Alarm if door is in closed position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o237 | Alarm if vehicle loop 1 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o238 | Alarm if vehicle loop 2 is activated |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |


| o239 | Alarm if photocell interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o242 | Alarm for uncritical error message in display. <br> E008, E015, E028, E046, E047, E048, E201, E202, <br> E206, E207, E931, E932 | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o283 | Inversion of contact function for output |  |  | $1-2$ | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Normally open, NO |  |  |  |
|  | 2 | Normally closed, NC |  |  |  |


| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o291 | Function when SL.1, SL. 2 or photocell/loop activated |  | 01-14 | 01 |  |
|  | 01 | Presence detection. Signal when LOOP1 is activated, remains until LOOP1 is clear. |  |  |  |
|  | 02 | Presence detection. Signal when LOOP2 is activated, remains until LOOP2 is clear. |  |  |  |
|  | 03 | Presence detection. Signal when both LOOP1 and LOOP2 are activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 04 | Presence detection. Signal when PHOTO is activated, remains until PHOTO is clear. |  |  |  |
|  | 05 | Presence detection. Signal when PHOTO and LOOP1 are activated, remains until either PHOTO or LOOP1 is clear. |  |  |  |
|  | 06 | Presence detection. Signal when PHOTO and LOOP2 are activated, remains until either PHOTO or LOOP2 is clear. |  |  |  |
|  | 07 | Presence detection. Signal when PHOTO, LOOP1 and LOOP2 are activated, remains until either PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
|  | 08 | Presence detection. Signal when either LOOP1 or LOOP2 is activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 09 | Direction sensing. Signal when first LOOP1 and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |
|  | 10 | Direction sensing. Signal when first LOOP1 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 11 | Direction sensing. Signal when first LOOP2 and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 12 | Direction sensing. Signal when first LOOP2 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 13 | Direction sensing. Signal when first PHOTO and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 14 | Direction sensing. Signal when first PHOTO and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |

Programmable output 3
Note that the display of the o-channels is determined by the setting in C707 and C710

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o300 | Function of output 3 |  | 0-4 | 1 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Position indication/Movement/Warning. Signal as configured in o310-o322 |  |  |  |
|  | 2 | Presence detection/Direction sensing. Signal as configured in o391 |  |  |  |
|  | 3 | Lock |  |  |  |
|  | 4 | Alarm output. Signal as configured in o314, o330-o342 |  |  |  |


| o310 | Open position |  | $0-1$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o311 | Mid position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o312 | Closed position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o313 | Movement |  |  | $0-4$ | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal in the opening movement |  |  |  |
|  | 2 | Constant signal in the closing movement |  |  |  |
|  | 3 | Constant signal in the opening and closing movement |  |  |  |
|  | 4 | No signal during movement, used in combination with o310, o311 and o312. |  |  |  |


| o314 | Delayed switch-off Switch off after the specified time <br> Used for example for lighting that is switched off a <br> specified time after closing | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o320 | Pre-warning time before start | $000.0-600.0$ seconds | 000.0 |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| o321 | Pre-warning function in combination with o320 |  |  |  |  | $1-4$ | 2 |  |
|  | 1 | Constant signal before automatic closing |  |  |  |  |  |  |
|  | 2 | Constant signal before park and automatic closing |  |  |  |  |  |  |
|  | 3 | Constant signal before close signal, park and automatic closing |  |  |  |  |  |  |
|  | 4 | Constant signal before all movements |  |  |  |  |  |  |


| o322 | Function during pre-warning time in other output |  |  |  | $1-2$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Output signal disabled | 1 |  |  |
|  | 2 | Signal as configured in o310-o313 |  |  |  |



| o330 | Alarm delay. Alarm in channels o331 - o242 must be <br> active in this time to produce output signal. | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o331 | Alarm if pressed safety edge. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o332 | Alarm for critical error message in display | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o333 | Alarm if stop circuit interrupted |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o334 | Alarm if door open | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o335 | Alarm if door is in mid position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o336 | Alarm if door is in closed position |  |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |  |
|  | 1 | Constant signal |  |  |  |  |  |  |  |  |


| o337 | Alarm if vehicle loop 1 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o338 | Alarm if vehicle loop 2 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o339 | Alarm if photocell interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o342 | Alarm for uncritical error message in display. <br> E008, E015, E028, E046, E047, E048, E201, E202, <br> E206, E207, E931, E932 | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o383 | Inversion of contact function for output |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Normally open, NO |  |  |  |  |  |  |  |
|  | 2 | Normally closed, NC |  |  |  |  |  |  |  |


| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o391 | Function when SL.1, SL. 2 or photocell/loop activated |  | 01-14 | 01 |  |
|  | 01 | Presence detection. Signal when LOOP1 is activated, remains until LOOP1 is clear. |  |  |  |
|  | 02 | Presence detection. Signal when LOOP2 is activated, remains until LOOP2 is clear. |  |  |  |
|  | 03 | Presence detection. Signal when both LOOP1 and LOOP2 are activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 04 | Presence detection. Signal when PHOTO is activated, remains until PHOTO is clear. |  |  |  |
|  | 05 | Presence detection. Signal when PHOTO and LOOP1 are activated, remains until either PHOTO or LOOP1 is clear. |  |  |  |
|  | 06 | Presence detection. Signal when PHOTO and LOOP2 are activated, remains until either PHOTO or LOOP2 is clear. |  |  |  |
|  | 07 | Presence detection. Signal when PHOTO, LOOP1 and LOOP2 are activated, remains until either PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
|  | 08 | Presence detection. Signal when either LOOP1 or LOOP2 is activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 09 | Direction sensing. Signal when first LOOP1 and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |
|  | 10 | Direction sensing. Signal when first LOOP1 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 11 | Direction sensing. Signal when first LOOP2 and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 12 | Direction sensing. Signal when first LOOP2 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 13 | Direction sensing. Signal when first PHOTO and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 14 | Direction sensing. Signal when first PHOTO and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |

Programmable output 4
Note that the display of the o-channels is determined by the setting in C707 and C710


| o412 | Closed position |  |  | $0-2$ | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |
|  | $2^{*}$ | Invalid selection for DB410 (Flashing signal) |  |  |  |


| o413 | Movement |  |  | $0-7$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal in the opening movement |  |  |  |
|  | 2 | Constant signal in the closing movement |  |  |  |
|  | 3 | Constant signal in the opening and closing movement |  |  |  |
|  | No signal during movement, used in combination with o410, o411 and o412. |  |  |  |  |
|  | $5^{*}$ | Invalid selection for DB410 (Flashing signal in opening movement) |  |  |  |
|  | $6^{*}$ | Invalid selection for DB410 (Flashing signal in closing movement) |  |  |  |
|  | $7^{*}$ | Invalid selection for DB410 (Flashing signal in opening and closing movement) |  |  |  |


| o414 | Delayed switch-off Switch off after the specified time <br> Used for example for lighting that is switched off a <br> specified time after closing | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o420 | Pre-warning time before start |  | 000.0-600.0 seconds | 000.0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o421 | Pre-warning function in combination with o420 |  | 1-8 | 2 |  |
|  | 1 | Constant signal before automatic closing |  |  |  |
|  | 2 | Constant signal before park and automatic closing |  |  |  |
|  | 3 | Constant signal before close signal, park and automatic closing |  |  |  |
|  | 4 | Constant signal before all movements |  |  |  |
|  | 5* | Invalid selection for DB410 (Flashing signal before automatic closing) |  |  |  |
|  | 6* | Invalid selection for DB410 (Flashing signal before park and automatic closing) |  |  |  |
|  | 7* | Invalid selection for DB410 (Flashing signal before close signal, park and automatic closing) |  |  |  |
|  | 8* | Invalid selection for DB410 (Flashing signal before all movements) |  |  |  |

* WARNING! This setting is possible, but NOT permitted! Selecting it means that the relay output will cease to function. The channel selection for flashing function may be used only together with DB407.


| o430 | Alarm delay. Alarm in channels o431 - o442 must be <br> active in this time to produce output signal. | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |
| o431 | Alarm if pressed safety edge. | $0-1$ | 0 |  |
|  | 0 | Constant signal |  |  |
|  | 1 | Active |  |  |


| o432 | Alarm for critical error message in display | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Constant signal |  |  |
|  | 1 | Active |  |  |


| o433 | Alarm if stop circuit interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o434 | Alarm if door open | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| 435 | Alarm if door is in mid position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o436 | Alarm if door is in closed position |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o437 | Alarm if vehicle loop 1 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o438 | Alarm if vehicle loop 2 is activated |  |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |  |
|  | 1 | Constant signal |  |  |  |  |  |  |  |  |


| o439 | Alarm if photocell interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o442 | Alarm for uncritical error message in display. <br> E008, E015, E028, E046, E047, E048, E201, E202, <br> E206, E207, E931, E932 | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o483 | Inversion of contact function for output |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Normally open, NO |  |  |  |  |  |  |  |
|  | 2 | Normally closed, NC |  |  |  |  |  |  |  |

No. Name

| o491 | Function when LOOP2, LOOP2 or PHOTO <br> activated | Range | $01-14$ | 01 |
| :--- | :--- | :--- | :--- | :--- |
|  | 01 | Presence detection Signal when LOOP1 is activated, remains until LOOP1 is clear. |  |  |
| 02 | Presence detection Signal when LOOP2 is activated, remains until LOOP2 is clear. |  |  |  |
| 03 | Presence detection. Signal when both LOOP1 and LOOP2 are activated, remains until either LOOP1 <br> or LOOP2 is clear. |  |  |  |
| 04 | Presence detection. Signal when PHOTO is activated, remains until PHOTO is clear. |  |  |  |
| 05 | Presence detection. Signal when PHOTO and LOOP1 are activated, remains until either PHOTO or <br> LOOP1 is clear. |  |  |  |
| 06 | Presence detection. Signal when PHOTO and LOOP2 are activated, remains until either PHOTO or <br> LOOP2 is clear. |  |  |  |
| 07 | Presence detection. Signal when PHOTO, LOOP1 and LOOP2 are activated, remains until either <br> PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
| 08 | Presence detection. Signal when either LOOP1 or LOOP2 is activated, remains until either LOOP1 or <br> LOOP2 is clear. |  |  |  |
| 09 | Direction sensing. Signal when first LOOP1 and then LOOP2 are activated. The signal remains until <br> LOOP2 is clear. |  |  |  |
| 10 | Direction sensing. Signal when first LOOP1 and then PHOTO are activated. The signal remains until <br> PHOTO is clear. |  |  |  |
| 11 | Direction sensing. Signal when first LOOP2 and then LOOP1 are activated. The signal remains until <br> LOOP1 is clear. |  |  |  |
| 12 | Direction sensing. Signal when first LOOP2 and then PHOTO are activated. The signal remains until <br> PHOTO is clear. |  |  |  |
| 13 | Direction sensing. Signal when first PHOTO and then LOOP1 are activated. The signal remains until <br> LOOP1 is clear. |  |  |  |
| 14 | Direction sensing. Signal when first PHOTO and then LOOP2 are activated. The signal remains until <br> LOOP2 is clear. |  |  |  |

Programmable output 5
Note that the display of the o-channels is determined by the setting in C707 and C710

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o500 | Function of output 1 |  | 0-4 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Position indication/Movement/Warning. Signal as configured in o510-o522 |  |  |  |
|  | 2 | Presence detection/Direction sensing. Signal as configured in o591 |  |  |  |
|  | 3 | Lock |  |  |  |
|  | 4 | Alarm output. Signal as configured in o514, o530- o542 |  |  |  |
| o510 | Open position |  | 0-1 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o511 | Mid position |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o512 | Closed position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o513 | Movement |  |  | $0-4$ | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal in the opening movement |  |  |  |
|  | 2 | Constant signal in the closing movement |  |  |  |
|  | 3 | Constant signal in the opening and closing movement |  |  |  |
|  | 4 | No signal during movement, used in combination with o510, o511 and o512. |  |  |  |


| o514 | Delayed switch-off Switch off after the specified time <br> Used for example for lighting that is switched off a <br> specified time after closing | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o520 | Pre-warning time before start | $000.0-600.0$ seconds | 000.0 |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| o521 | Pre-warning function in combination with o520 |  |  |  |  | $1-4$ | 2 |  |
|  | 1 | Constant signal before automatic closing |  |  |  |  |  |  |
|  | 2 | Constant signal before park and automatic closing |  |  |  |  |  |  |
|  | 3 | Constant signal before close signal, park and automatic closing |  |  |  |  |  |  |
|  | 4 | Constant signal before all movements |  |  |  |  |  |  |


| o522 | Function during pre-warning time in other output |  |  |  | $1-2$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Output signal disabled | 1 |  |  |
|  | 2 | Output signal as configured in o510-o512 |  |  |  |



| o530 | Alarm delay. Alarm in channels o531 - o542 must be <br> active in this time to produce output signal. | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| o531 | Alarm if pressed safety edge. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o532 | Alarm for critical error message in display | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o533 | Alarm if stop circuit interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o534 | Alarm if door open | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o535 | Alarm if door is in mid position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o536 | Alarm if door is in closed position |  |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |  |
|  | 1 | Constant signal |  |  |  |  |  |  |  |  |


| o537 | Alarm if vehicle loop 1 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o538 | Alarm if vehicle loop 2 is activated | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o539 | Alarm if photocell interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o542 | Alarm for uncritical error message in display. <br> E008, E015, E028, E046, E047, E048, E201, E202, <br> E206, E207, E931, E932 | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o583 | Inversion of contact function for output |  |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 1 | Normally open, NO |  |  |  |  |  |  |  |  |
|  | 2 | Normally closed, NC |  |  |  |  |  |  |  |  |


| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o591 | Function when LOOP2, LOOP2 or PHOTO activated |  | 01-14 | 01 |  |
|  | 01 | Presence detection. Signal when LOOP1 is activated, remains until LOOP1 is clear. |  |  |  |
|  | 02 | Presence detection. Signal when LOOP2 is activated, remains until LOOP2 is clear. |  |  |  |
|  | 03 | Presence detection. Signal when both LOOP1 and LOOP2 are activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 04 | Presence detection. Signal when PHOTO is activated, remains until PHOTO is clear. |  |  |  |
|  | 05 | Presence detection. Signal when PHOTO and LOOP1 are activated, remains until either PHOTO or LOOP1 is clear. |  |  |  |
|  | 06 | Presence detection. Signal when PHOTO and LOOP2 are activated, remains until either PHOTO or LOOP2 is clear. |  |  |  |
|  | 07 | Presence detection. Signal when PHOTO, LOOP1 and LOOP2 are activated, remains until either PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
|  | 08 | Presence detection. Signal when either LOOP1 or LOOP2 is activated, remains until either LOOP1 or LOOP2 is clear. |  |  |  |
|  | 09 | Direction sensing. Signal when first LOOP1 and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |
|  | 10 | Direction sensing. Signal when first LOOP1 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 11 | Direction sensing. Signal when first LOOP2 and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 12 | Direction sensing. Signal when first LOOP2 and then PHOTO are activated. The signal remains until PHOTO is clear. |  |  |  |
|  | 13 | Direction sensing. Signal when first PHOTO and then LOOP1 are activated. The signal remains until LOOP1 is clear. |  |  |  |
|  | 14 | Direction sensing. Signal when first PHOTO and then LOOP2 are activated. The signal remains until LOOP2 is clear. |  |  |  |

Programmable output 6
Note that the display of the o-channels is determined by the setting in C707 and C710

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| o600 | Function of output 1 |  | 0-4 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Position indicati | s configu |  |  |
|  | 2 | Presence detecti | configured |  |  |
|  | 3 | Lock |  |  |  |
|  | 4 | Alarm output. S | -o642 |  |  |
| o610 | Open position |  | 0-1 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o611 | Mid position |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o612 | Closed position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal. |  |  |


| 0613 | Movement |  |  | $0-4$ | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal in the opening movement |  |  |  |
|  | 2 | Constant signal in the closing movement |  |  |  |
|  | 3 | Constant signal in the opening and closing movement |  |  |  |
|  | 4 | No signal during movement, used in combination with o610, o611 and o612. |  |  |  |


| o614 | Delayed switch-off Switch off after the specified time <br> Used for example for lighting that is switched off a <br> specified time after closing | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |


| 0620 | Pre-warning time before start | $000.0-600.0$ seconds | 000.0 |  |
| :--- | :--- | :--- | :--- | :--- |
| 0621 |  |  |  |  |
|  | 1 | Pre-warning function in combination with o620 | $1-4$ | 2 |


| o622 | Function during pre-warning time in other output |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | $1-2$ | 1 |  |  |
|  | 2 | Output signal disabled |  |  |  |



| o631 | Alarm if pressed safety edge. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o632 | Alarm for critical error message in display | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o633 | Alarm if stop circuit interrupted |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |
|  | 1 | Constant signal |  |  |  |  |  |  |  |


| o634 | Alarm if door open | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o635 | Alarm if door is in mid position |  |  |  |  |  | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |
|  | 1 | Constant signal |  |  |  |  |  |  |  |


| 0636 | Alarm if door is in closed position | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o637 | Alarm if vehicle loop 1 is activated |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| 0638 | Alarm if vehicle loop 2 is activated |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Constant signal |  |  |  |


| o639 | Alarm if photocell interrupted | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o642 | Alarm for uncritical error message in display. <br> E008, E015, E028, E046, E047, E048, E201, E202, <br> E206, E207, E931, E932 | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Constant signal |  |  |


| o683 | Inversion of contact function for output |  |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
|  | 1 | Normally open, NO |  |  |  |  |  |  |  |  |
|  | 2 | Normally closed, NC |  |  |  |  |  |  |  |  |

No. Name

| o691 | Function when LOOP2, LOOP2 or PHOTO <br> activated | Range | $01-14$ | 01 |
| :--- | :--- | :--- | :--- | :--- |
|  | 01 | Presence detection. Signal when LOOP1 is activated, remains until LOOP1 is clear. |  |  |
| 02 | Presence detection. Signal when LOOP2 is activated, remains until LOOP2 is clear. |  |  |  |
| 03 | Presence detection. Signal when both LOOP1 and LOOP2 are activated, remains until either LOOP1 <br> or LOOP2 is clear. |  |  |  |
| 04 | Presence detection. Signal when PHOTO is activated, remains until PHOTO is clear. |  |  |  |
| 05 | Presence detection. Signal when PHOTO and LOOP1 are activated, remains until either PHOTO or <br> LOOP1 is clear. |  |  |  |
| 06 | Presence detection. Signal when PHOTO and LOOP2 are activated, remains until either PHOTO or <br> LOOP2 is clear. |  |  |  |
| 07 | Presence detection. Signal when PHOTO, LOOP1 and LOOP2 are activated, remains until either <br> PHOTO, LOOP1 or LOOP2 is clear. |  |  |  |
| 08 | Presence detection. Signal when either LOOP1 or LOOP2 is activated, remains until either LOOP1 or <br> LOOP2 is clear. |  |  |  |
| 09 | Direction sensing. Signal when first LOOP1 and then LOOP2 are activated. The signal remains until <br> LOOP2 is clear. |  |  |  |
| 10 | Direction sensing. Signal when first LOOP1 and then PHOTO are activated. The signal remains until <br> PHOTO is clear. |  |  |  |
| 11 | Direction sensing. Signal when first LOOP2 and then LOOP1 are activated. The signal remains until <br> LOOP1 is clear. |  |  |  |
| 12 | Direction sensing. Signal when first LOOP2 and then PHOTO are activated. The signal remains until <br> PHOTO is clear. |  |  |  |
| 13 | Direction sensing. Signal when first PHOTO and then LOOP1 are activated. The signal remains until <br> LOOP1 is clear. |  |  |  |
| 14 | Direction sensing. Signal when first PHOTO and then LOOP2 are activated. The signal remains until <br> LOOP2 is clear. |  |  |  |

- Programmable inputs, $P$ channels

Programmable input 1

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| P100 | Programmable input 1 |  | 0-1 | 1 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Enabled |  |  |  |
| P160 | Control function |  | 0-5 | 1 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |
|  | 2 | Close |  |  |  |
|  | 3 | Stop |  |  |  |
|  | 4 | Open/Close |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |
| $\triangle$ P161 | Type of control signal when activated |  | 1-2 | 1 |  |
|  | 1 | Pulse (hold-to-run mode not possible) |  |  |  |
|  | 2 | Signal for as long as the input is activated |  |  |  |
| P162 | Motor selection |  | 1-3 | 3 |  |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |
| P163 | Partial opening |  | 0-1 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 has expired. |  |  |  |


| P170 | Motor lock | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | The gate cannot be operated without a signal at programmable input 1. <br> If the signal disappears ongoing movement stops. |  |  |

## P175 $\quad$ Opening via input after activation during set time, input will not open the gate until it has been activated for the set time.



| P180 | Park |  |  | $0-2$ | 2 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Automatic closing disabled after the input is activated, reset by another control signal |  |  |  |
|  | 2 | Automatic closing disabled by a constant signal. |  |  |  |


| P190 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if P160 is set to 1, "Open" |  |  |


| P196 | Blocking disabled for local and remote doors. <br> Works only with a constant signal. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C614 |  |  |
|  | 1 | Blocking disabled |  |  |


| P198 | Automatic closing switched off for remote door. <br> Works only if there is a constant signal | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C500 |  |  |
|  | 1 | Automatic closing switched off |  |  |

Programmable input 2


| $\triangle$ P261 | Type of control signal when activated |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Pulse (hold-to-run mode not possible) | $1-2$ |  |  |
|  | 2 | Signal for as long as the input is activated |  |  |  |


| P262 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |


| P263 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |
|  | 1 |  |  |  |


| P270 | Motor lock | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | The gate cannot be operated without a signal at programmable input 2. <br> If the signal disappears ongoing movement stops. |  |  |


| P275 | Opening via input after activation during set time, <br> input will not open the gate until it has been activated <br> for the set time. | $0.0-9.9$ seconds | 0.0 |  |
| :--- | :--- | :--- | :--- | :--- |
| P280 | Park | $0-2$ | 0 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Automatic closing disabled after the input is activated, reset by another control signal |  |  |
|  | 2 | Automatic closing disabled by a constant signal |  |  |


| P290 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if P260 is set to 1, "Open" |  |  |


| P296 | Blocking disabled for local and remote doors. <br> Works only with a constant signal. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C614 |  |  |
|  | 1 | Blocking disabled |  |  |


| P298 | Automatic closing switched off for remote door. <br> Works only if there is a constant signal | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C500 |  |  |
|  | 1 | Automatic closing switched off |  |  |

Programmable input 3


| $\triangle$ P361 | Type of control signal when activated |  |  |  |  |  | $1-2$ | $\mathbf{2}$ |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Pulse (hold-to-run mode not possible) |  |  |  |  |  |  |  |
|  | 2 | Signal for as long as the input is activated |  |  |  |  |  |  |  |


| P362 | Motor selection |  |  |  |  |  | $1-3$ | 3 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Motor 1 |  |  |  |  |  |  |  |
|  | 2 | Motor 2 |  |  |  |  |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |  |  |  |  |


| P363 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |  |


| P370 | Motor lock | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | The gate cannot be operated without a signal at programmable input 3. <br> If the signal disappears ongoing movement stops. |  |  |


| P375 | Opening via input after activation during set time, <br> input will not open the gate until it has been activated <br> for the set time. | $0.0-9.9$ seconds | 0.0 |  |
| :--- | :--- | :--- | :--- | :--- |
| P380 | Park | $0-2$ | 0 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Automatic closing disabled after the input is activated, reset by another control signal |  |  |
|  | 2 | Automatic closing disabled by a constant signal. |  |  |


| P390 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if P360 is set to 1, "Open" |  |  |


| P396 | Blocking disabled for local and remote doors. <br> Works only with a constant signal. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C614 |  |  |
|  | 1 | Blocking disabled |  |  |


| P398 | Automatic closing switched off for remote door. <br> Works only if there is a constant signal | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C500 |  |  |
|  | 1 | Automatic closing switched off |  |  |

## Programmable input 4

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| P400 | Programmable input 4 |  | 0-1 | 1 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Enabled |  |  |  |
| P460 | Control function |  | 0-5 | 2 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |
|  | 2 | Close |  |  |  |
|  | 3 | Stop |  |  |  |
|  | 4 | Open/Close |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |


| $\triangle$ P461 | Type of control signal when activated |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Pulse | $\mathbf{2}-2$ |  |  |
|  | 2 | Signal for as long as the input is activated |  |  |  |


| P462 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |


| P463 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |
|  | 1 |  |  |  |


| P470 | Motor lock | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | The gate cannot be operated without a signal at programmable input 4. <br> If the signal disappears ongoing movement stops. |  |  |


| P475 | Opening via input after activation during set time, <br> input will not open the gate until it has been activated <br> for the set time. | $0.0-9.9$ seconds | 0.0 |  |
| :--- | :--- | :--- | :--- | :--- |
| P480 | Park | $0-2$ | 0 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Automatic closing disabled after the input is activated, reset by another control signal |  |  |
|  | 2 | Automatic closing disabled by a constant signal. |  |  |


| P490 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if P460 is set to 1, "Open" |  |  |


| P496 | Blocking disabled for local and remote doors. <br> Works only with a constant signal. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C614 |  |  |
|  | 1 | Blocking disabled |  |  |


| P498 | Automatic closing switched off for remote door. <br> Works only if there is a constant signal | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C500 |  |  |
|  | 1 | Automatic closing switched off |  |  |

Programmable input 5

| No. | Name | Range | Factory | Setting |
| :--- | :--- | :--- | :--- | :--- | :--- |
| P500 | Programmable input 5 | $0-1$ | 1 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Activated (Only channels P560-P598 activated) |  |  |
|  | 2 | Battery operation, only together with frequency converter (Channels P560-P598 inactivated) |  |  |


| P560 | Control function | $0-5$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Open |  |  |
|  | 2 | Close |  |  |
|  | 3 | Stop |  |  |
|  | 4 | Open/Close |  |  |
|  | 5 | Open/Stop/Close |  |  |


| $\triangle$ P561 | Type of control signal when activated |  |  |  |  |  | $1-2$ | 1 |  |
| :---: | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Pulse |  |  |  |  |  |  |  |
|  | 2 | Signal for as long as the input is activated |  |  |  |  |  |  |  |


| P562 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |


| P563 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |
|  | 1 |  |  |  |


| P570 | Motor lock | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | The gate cannot be operated without a signal at programmable input 5. <br> If the signal disappears ongoing movement stops. |  |  |


| P575 | Opening via input after activation during set time, <br> input will not open the gate until it has been activated <br> for the set time. | $0.0-9.9$ seconds | 0.0 |  |
| :--- | :--- | :--- | :--- | :--- |
| P580 | Park | $0-2$ | 0 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Automatic closing disabled after the input is activated, reset by another control signal |  |  |
|  | 2 | Automatic closing disabled by a constant signal. |  |  |


| P590 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if P560 is set to 1, "Open" |  |  |


| P596 | Blocking disabled for local and remote doors. <br> Works only with a constant signal. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C614 |  |  |
|  | 1 | Blocking disabled |  |  |


| P598 | Automatic closing switched off for remote door. <br> Works only if there is a constant signal | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, function according to channel C500 |  |  |
|  | 1 | Automatic closing switched off |  |  |

Programmable input 6

| No. | Name | Range | Factory | Setting |
| :--- | :--- | :--- | :--- | :--- |
| P600 | Programmable input 6 | $0-1$ | 1 |  |
|  | 0 | Disabled |  |  |
|  | 1 | Activated (Only channels P660-P698 activated) |  |  |
|  | 2 | Safety input (Only channels P640-P643 activated) |  |  |


| P640 | Safety function when input is activated |  |  | $0-3$ | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Reverse to fully open |  |  |  |
|  | 2 | Stop with automatic restart of automatic closing |  |  |  |
|  | 3 | Stop, wait for new control signal or time in C520 and thereafter automatic closing. |  |  |  |


| P641 | Safety during run-on time or disengagement angle in <br> closing movement. | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled when both halves are in run-on or disengagement angle |  |  |
|  | 1 | Activated according to P640 |  |  |


| P642 | Protection in opening movement |  |  |  | $0-4$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | 1 |  |  |
|  | 1 | Reverse to fully closed |  |  |  |
|  | 2 | Stop with automatic restart of automatic closing |  |  |  |
|  | 3 | Stop, wait for new control signal or time in C520 and then automatic closing. |  |  |  |
|  | 4 | Stop with restart of opening |  |  |  |


| P643 | Control of external protection connected to INP6 |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | No check | 1 |  |  |
|  | 1 | Test of break in continuity for protection connected to INP6 |  |  |  |


| P660 | Control function |  |  |  |  |  | $0-5$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 0 | Disabled |  |  |  |  |  |  |  |
|  | 1 | Open |  |  |  |  |  |  |  |
|  | 2 | Close |  |  |  |  |  |  |  |
|  | 3 | Stop |  |  |  |  |  |  |  |
|  | 4 | Open/Close |  |  |  |  |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |  |  |  |  |


| $\triangle$ P661 | Type of control signal when activated |  |  |  |  |  | $1-2$ | 1 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Pulse |  |  |  |  |  |  |  |
|  | 2 | Signal for as long as the input is activated |  |  |  |  |  |  |  |


| P662 | Motor selection |  |  |  |  |  | $1-3$ | 3 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Motor 1 |  |  |  |  |  |  |  |
|  | 2 | Motor 2 |  |  |  |  |  |  |  |
|  | 3 | Motors 1 and 2 |  |  |  |  |  |  |  |


| P663 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |  |


| P670 | Motor lock | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | The gate cannot be operated without a signal at programmable input 6. <br> If the signal disappears ongoing movement stops. |  |  |



- Radio DB411, r-channels

Programmable radio input 1
Note that the display of the r-channels is determined by the setting in C711

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| r001 | Readout of received radio input |  | 0-4 |  |  |
|  | 0 | No radio reception |  |  |  |
|  | 1 | Radio input 1 is receiving |  |  |  |
|  | 2 | Radio input 2 is receiving |  |  |  |
|  | 3 | Radio input 3 is receiving |  |  |  |
|  | 4 | Radio input 4 is receiving |  |  |  |
| r160 | Control function |  | 0-5 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |
|  | 2 | Close |  |  |  |
|  | 3 | Stop |  |  |  |
|  | 4 | Open/close |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |


| r162 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motor 1 and Motor 2 |  |  |  |


| r163 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |
|  | 1 |  |  |  |


| r170 | Disable operation at radio input 1. |  |  | $0-6$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, normal operation. (Programmable input has no function for radio input 1) |  |  |
|  | 1 | Operate only if there is a signal at programmable input 1 |  |  |
|  | 2 | Operate only if there is a signal at programmable input 2 |  |  |
|  | 3 | Operate only if there is a signal at programmable input 3 |  |  |
|  | 4 | Operate only if there is a signal at programmable input 4 |  |  |
|  | 5 | Operate only if there is a signal at programmable input 5 |  |  |
|  | 6 | Operate only if there is a signal at programmable input 6 |  |  |


| r180 | Park | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Park without automatic closing. Reset by another control signal |  |  |


| r190 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if r160 is set to 1, "Open" |  |  |

Programmable wireless input 2
Note that the display of the r-channels is determined by the setting in C711

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| r001 | Readout of received wireless input |  | 0-4 |  |  |
|  | 0 | No radio reception |  |  |  |
|  | 1 | Radio input 1 is receiving a radio signal |  |  |  |
|  | 2 | Radio input 2 is receiving a radio signal |  |  |  |
|  | 3 | Radio input 3 is receiving a radio signal |  |  |  |
|  | 4 | Radio input 4 is receiving a radio signal |  |  |  |
| r260 | Control function |  | 0-5 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |
|  | 2 | Close |  |  |  |
|  | 3 | Stop |  |  |  |
|  | 4 | Open/close |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |


| r262 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motor 1 and Motor 2 |  |  |  |


| r263 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |
|  | 1 |  |  |  |


| r270 | Disable operation at radio input 2. |  |  | $0-6$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, normal operation. (Programmable input has no function for radio input 2) |  |  |
|  | 1 | Operate only if there is a signal at programmable input 1 |  |  |
|  | 2 | Operate only if there is a signal at programmable input 2 |  |  |
|  | 3 | Operate only if there is a signal at programmable input 3 |  |  |
|  | Operate only if there is a signal at programmable input 4 |  |  |  |
|  | 5 | Operate only if there is a signal at programmable input 5 |  |  |
|  | 6 | Operate only if there is a signal at programmable input 6 |  |  |


| r280 | Park |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Park without automatic closing. Reset by another control signal |  |  |  |


| r290 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if r260 is set to 1, "Open" |  |  |

## Programmable wireless input 3

Note that the display of the r-channels is determined by the setting in C711

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| r001 | Readout of received radio input |  | 0-4 | 0 |  |
|  | 0 | No radio reception |  |  |  |
|  | 1 | Radio input 1 is receiving a radio signal |  |  |  |
|  | 2 | Radio input 2 is receiving a radio signal |  |  |  |
|  | 3 | Radio input 3 is receiving a radio signal |  |  |  |
|  | 4 | Radio input 4 is receiving a radio signal |  |  |  |
| r360 | Control function |  | 0-5 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |
|  | 2 | Close |  |  |  |
|  | 3 | Stop |  |  |  |
|  | 4 | Open/close |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |


| r362 | Motor selection |  |  |  |  |  | $1-3$ | 3 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | 1 | Motor 1 |  |  |  |  |  |  |  |
|  | 2 | Motor 2 |  |  |  |  |  |  |  |
|  | 3 | Motor 1 and Motor 2 |  |  |  |  |  |  |  |


| r363 | Partial opening |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |  |  |


| r370 | Disable operation at wireless input 3. |  |  | $0-6$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, normal operation. (Programmable input has no function for radio input 3) |  |  |
|  | 1 | Operate only if there is a signal at programmable input 1 |  |  |
|  | 2 | Operate only if there is a signal at programmable input 2 |  |  |
|  | 3 | Operate only if there is a signal at programmable input 3 |  |  |
|  | Operate only if there is a signal at programmable input 4 |  |  |  |
|  | 5 | Operate only if there is a signal at programmable input 5 |  |  |
|  | 6 | Operate only if there is a signal at programmable input 6 |  |  |


| r380 | Park |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Park without automatic closing. Reset by another control signal |  |  |  |


| r390 | Interlock opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |
|  | 1 | Sends open signal to remote door, if r 360 is set to 1, "Open" |  |  |

Programmable wireless input 4
Note that the display of the r-channels is determined by the setting in C711

| No. | Name |  | Range | Factory | Setting |
| :---: | :---: | :---: | :---: | :---: | :---: |
| r001 | Readout of received wireless input |  | 0-4 |  |  |
|  | 0 | No radio reception |  |  |  |
|  | 1 | Radio input 1 is receiving a radio signal |  |  |  |
|  | 2 | Radio input 2 is receiving a radio signal |  |  |  |
|  | 3 | Radio input 3 is receiving a radio signal |  |  |  |
|  | 4 | Radio input 4 is receiving a radio signal |  |  |  |
| r460 | Control function |  | 0-5 | 0 |  |
|  | 0 | Disabled |  |  |  |
|  | 1 | Open |  |  |  |
|  | 2 | Close |  |  |  |
|  | 3 | Stop |  |  |  |
|  | 4 | Open/close |  |  |  |
|  | 5 | Open/Stop/Close |  |  |  |


| r462 | Motor selection |  |  | $1-3$ | 3 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | Motor 1 |  |  |  |
|  | 2 | Motor 2 |  |  |  |
|  | 3 | Motor 1 and Motor 2 |  |  |  |


| r463 | Partial opening | $0-1$ | 0 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled | Opening according to set time in channel L216/L226 or number of degrees in L116/L126 if encoder <br> is used. During partial opening, closing and opening maneuvers will be paused until the time in C500 <br> has expired. |  |
|  | 1 |  |  |  |


| r470 | Disable operation at wireless input 4. |  |  | $0-6$ |
| :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled, normal operation. (Programmable input has no function for radio input 4) |  |  |
|  | 1 | Operate only if there is a signal at programmable input 1 |  |  |
|  | 2 | Operate only if there is a signal at programmable input 2 |  |  |
|  | Operate only if there is a signal at programmable input 3 |  |  |  |
|  | Operate only if there is a signal at programmable input 4 |  |  |  |
|  | 5 | Operate only if there is a signal at programmable input 5 |  |  |
|  | 6 | Operate only if there is a signal at programmable input 6 |  |  |


| r480 | Park |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Park without automatic closing. Reset by another control signal |  |  |  |


| r490 | Interlock opening |  |  | $0-1$ | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 0 | Disabled |  |  |  |
|  | 1 | Sends open signal to remote door, if r460 is set to 1, "Open" |  |  |  |

## Error messages in display and in the error code list in channel C903

Grey background means that the automatic control unit must be restarted (power off) in order to reset the error message.

| Error code | Meaning | Possible cause |
| :---: | :---: | :---: |
| EP-1 | Not an error code - indicates the type of EP105 in use |  |
| EP-2 | Not an error code - indicates the type of EP105 in use |  |
| E000 | No error, shown to acknowledge a change in the service channel. |  |
| E003 | Limited running time exceeded | Gears slipping? Check L203 |
| E008 | Momentary loss of 24 V | Mains failure, momentary 24 V short circuit. |
| E015 | Momentary loss of 230 V | Has there been a power failure? |
| E016 | Loss of mains power 230 V | Has there been a power failure? |
| E017 | Safety edge or load guard triggered five times in succession | It something preventing the door reaching the closed position? |
| E020 | Voltage too high in safety circuit | The voltage measured by the automatic control unit is too high. |
| E021 | Voltage too low in safety circuit | Poor contact between connected stop buttons on terminals 7-12? |
| E025 | Incorrect setting for personal protection, motor 1 | Check C200 and C230, the load guard cannot be disabled with personal protection activated. Check C211, it cannot be longer than 0.06 seconds. C212 cannot be longer than 2 seconds. C493 cannot be longer than 0.20 seconds. |
| E026 | Incorrect setting for personal protection, motor 2 | Check C200 and C240, the load guard cannot be disabled with personal protection activated. Check C211, it cannot be longer than 0.06 seconds. C212 cannot be longer than 2 seconds. C493 cannot be longer than 0.20 seconds. |
| E028 | Brake selected when C202 is set to 2, 4 or 5 | Check that C495/C496 is set to 0 . |
| E032 | Limit switch L.O1 has lost its position | Is the limit switch cam bypassing the switch? Loose connection in switch? |
| E033 | Limit switch L.C1 has lost its position | Is the limit switch cam bypassing the switch? Loose connection in switch? |
| E034 | Limit switch L.O2 has lost its position | Is the limit switch cam bypassing the switch? Loose connection in switch? |
| E035 | Limit switch L.C2 has lost its position | Is the limit switch cam bypassing the switch? Loose connection in switch? |
| E044 | Hidden channels shown |  |
| E046 | Opening counter reset |  |
| E047 | Factory reset of all channels |  |
| E048 | Error code list reset |  |
| E053 | Unknown circuit board version | Contact FAAC Nordic AB |
| E116 | No safety edge acknowledgement | Only applies to up-and-over control, fault in safety edge? Correct run-on time? |
| E141 | SE.O2 is disabled when C104 is set to 3 | Indication function of SE.O2 in channel C141 |
| E201 | Motor protection triggered for motor 1 | Motor is taking more than 1.5 x motor current. Motor is sluggish or stops. Faulty fuse? Phase failure in an incoming |
| E202 | Motor protection triggered for motor 2 | phase? Break in cable to motor or motor winding? Check the motor protection setting. |
| E203 | Motor protection triggered four times in a row, control unit locked for 3 minutes | Is there an obstacle? Fault in electric motor? Check the configuration of channels C252, C253, C262, C263. |
| E204 | Current through motor 1, which is switched off |  |
| E205 | Current through motor 2, which is switched off |  |


| Error code | Meaning | Possible cause |
| :---: | :---: | :---: |
| E206 | No current or low current in motor 1 | The electric motor is running at less than half the motor protection setting. Check the motor protection setting. Phase |
| E207 | No current or low current in motor 2 | electric motor? Voltage drop in stop circuit/limit switch circuit? |
| E221 | Start load too low, motor 1 | Check that the motor is correctly connected and that the value in C230 agrees with C231. |
| E222 | Start load too low, motor 2 | Check that the motor is correctly connected and that the value in C240 agrees with C241. |
| E223 | Normal power too low, motor 1 | Check C230. |
| E224 | Normal power too low, motor 2 | Check C240. |
| E225 | The load guard has been tripped three times in a row | Obstacle in the way? Mechanical fault preventing closing? Check the load guard settings. |
| E318 | Error in loop 1 | Are the loop and connectors electrically continuo |
| E319 | Error in loop 2 | For more troubleshooting tips, see the instruction manual for the vehicle detector |
| E614 | Communication error | Correct polarity in communication cables? Break in communication cable? Correct settings in both automatic control units? Is the external unit switched on? |
| E651 | No response from frequency converter motor 1 | Check the connection and the settings as described in Instruction Manual for DB409. Address must be set for the frequency converter. |
| E652 | No response from frequency converter motor 2 | Check the connection and the settings as described in Instruction Manual for DB409. Address must be set for the frequency converter. |
| E661 | Incorrect value sent to frequency converter for motor 1 | Contact FAAC Nordic AB |
| E662 | Incorrect value sent to frequency converter for motor 2 | Contact FAAC Nordic AB |
| E671 | Incorrect response from frequency converter for motor 1 | Contact FAAC Nordic AB |
| E672 | Incorrect response from frequency converter for motor 2 | Contact FAAC Nordic AB |
| E901 | Extraneous voltage at safety edge input SE.C1 | Contact FAAC Nordic AB. |
| E902 | Extraneous voltage at safety edge input SE.C2 | Contact FAAC Nordic AB. |
| E903 | Extraneous voltage at safety edge input SE.O1 | Contact FAAC Nordic AB. |
| E904 | Extraneous voltage at limit switch input | Contact FAAC Nordic AB. |
| E905 | Extraneous voltage in stop circuit | Contact FAAC Nordic AB. |
| E906 | Extraneous voltage at safety edge input SE.O2 | Contact FAAC Nordic AB. |
| E906 | Extraneous voltage on limit switch L.O1 | Contact FAAC Nordic AB. |
| E908 | Extraneous voltage on limit switch L.O2 | Contact FAAC Nordic AB. |
| E912 | Incorrect checksum in flash memory | Contact FAAC Nordic AB. |
| E913 | Memory error in RAM | Contact FAAC Nordic AB. |
| E914 | Memory error in EEPROM | Contact FAAC Nordic AB. |
| E915 | Incorrect EEPROM version | Contact FAAC Nordic AB. |
| E916 | Internal test not completed in time | Contact FAAC Nordic AB. |
| E917 | Incorrect order of execution | Contact FAAC Nordic AB. |
| E921 | Contactor for motor 1 activated before the previously activated contactor has been deactivated. | Contact FAAC Nordic AB. |
| E922 | Contactor for motor 2 activated before the previously activated contactor has been deactivated. | Contact FAAC Nordic AB. |
| E931 | Stop at the same time as an open/close operation. |  |


| Error code | Meaning | Possible cause |
| :---: | :---: | :---: |
| E932 | Open operation at the same time as a close operation. |  |
| E941 | Motor 1 running in the wrong direction according to the encoder setting. | Check that channel L110 is set to the correct side. Check the motor is running in the right direction. |
| E942 | Motor 2 running in the wrong direction according to the encoder setting. | Check that channel L120 is set to the correct side. Check the motor is running in the right direction. |
| E943 | No movement encoder 1 | Check connection to the encoder. |
| E944 | No movement encoder 2 | Check connection to the encoder. |
| E961 | SE.C1 did not change to low during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C113 to 0 . |
| E962 | SE.C2 did not change to low during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C123 to 0 . |
| E963 | SE.O1 did not change to low during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C133 to 0 . |
| E964 | PHOTO did not change to low during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C343 to 0 . |
| E965 | INP6 did not change to low during the external test. | Check that INP6 is working, if no self-test in the photocell, set channel P643 to 0 . |
| E966 | SE.O2 did not change to low during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C143 to 0 . |
| E971 | SE.C1 did not change to high during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C113 to 0 . |
| E972 | SE.C2 did not change to high during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C123 to 0 . |
| E973 | SE.O1 did not change to high during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C133 to 0 . |
| E976 | SE.O2 did not change to high during the external test. | Check that the safety edge is functional, if the safety edge is not functional, set channel C143 to 0 . |

## Messages in display and in the error code list in channel C903

| Code | Meaning |
| :--- | :--- |
| n 021 | Safety function for the photocell activated while opening |
| n 022 | Safety function for the photocell activated while closing |
| n 031 | Safety function for vehicle loop 1 activated while opening |
| n 032 | Safety function for vehicle loop 1 activated while closing |
| n 033 | Safety function for vehicle loop 2 activated while opening |
| n 034 | Safety function for vehicle loop 2 activated while closing |
| n 041 | Safety function for safety edge SE.O1 activated while opening |
| n042 | Safety function for safety edge SE.C1 activated while closing |
| n043 | Safety function for safety edge SE.O2 activated while opening |
| n044 | Safety function for safety edge SE.C2 activated while closing |
| n051 | Safety function for the photocell connected to programmable input 6 activated while opening |
| n052 | Safety function for the photocell connected to programmable input 6 activated while closing |
| n071 | Reverse due to load guard for motor 1 while opening |
| n072 | Reverse due to load guard for motor 1 while closing |
| n073 | Reverse due to load guard for motor 2 while opening |
| n 074 | Reverse due to load guard for motor 2 while closing |

## Troubleshooting

At each service, please check all the functions described in the relevant section on commissioning.

| Problem | Possible cause, tip |
| :--- | :--- |
| Error message in the display (Ennn) | See the section above on error messages. |
| The door reverses and the red LEDs M1/M2 start flashing. | $\begin{array}{l}\text { Is the load guard correctly installed? } \\ \text { Has the correct supply voltage been set? Mechanical fault? } \\ \text { Does the door move easily when decoupled? }\end{array}$ |
| Are the red LEDs SE.C1, SE.C2, SE.O1 or SE.O2 on or or |  |
| flashing? | $\begin{array}{l}\text { Check the channels for the safety edge value. Is the } \\ \text { impedance correct? } \\ \text { Adjust the safety edge switch if necessary? Are all the safety } \\ \text { edge units in use? Are any of the limit switch LEDs on? } \\ \text { The safety edge will not work unless the limit switches are } \\ \text { connected at the time the power is switched on. } \\ \text { Is the stop LED on? The safety edge will not work unless } \\ \text { the stop circuit is uninterrupted at the time the power is } \\ \text { switched on. }\end{array}$ |
| The door will not open or close. | $\begin{array}{l}\text { Are all the green LEDs that should be lit on? Have unused } \\ \text { stop inputs been jumpered? Are any of the LEDs INP1- }\end{array}$ |
| INP6 on? They should not usually be on (unless the system |  |
| is parked at certain times). The limit switch LEDs must light |  |
| up before the door can be operated. Example: L.O1 is on $=$ |  |
| motor 1 can start. The limit switches are connected in series |  |
| with the stop circuit. Fault/interruption in the wicket door |  |
| lontact or other contact in the stop circuit. Check that the |  |
| warning is configured. Check that the block is configured. |  |$\}$

## - Resetting/replacing tripped fuses

If the fuse protecting the power supply to the automatic control unit trips, FAAC Nordic AB recommends following these steps to reset/replace it.

- Switch off the main switch to the automatic control unit
- Decouple the drive unit.
- Reset or replace the fuse.
- Switch on the main switch to the automatic control unit.
- Check that none of the drive units start before receiving the control signal.
- Check that the drive units can be started and stopped from the control buttons.
- If the drive unit cannot be stopped, contact FAAC Nordic AB.


## Notes:

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